

**Part 1: Long-range active acoustic detection,
localization, tracking and classification for offshore
renewable energy applications
and**

**Part 2: Radiated noise measurements in a high-current
environment using a drifting noise measurement buoy**

Dr. Peter J. Stein

Scientific Solutions, Inc.

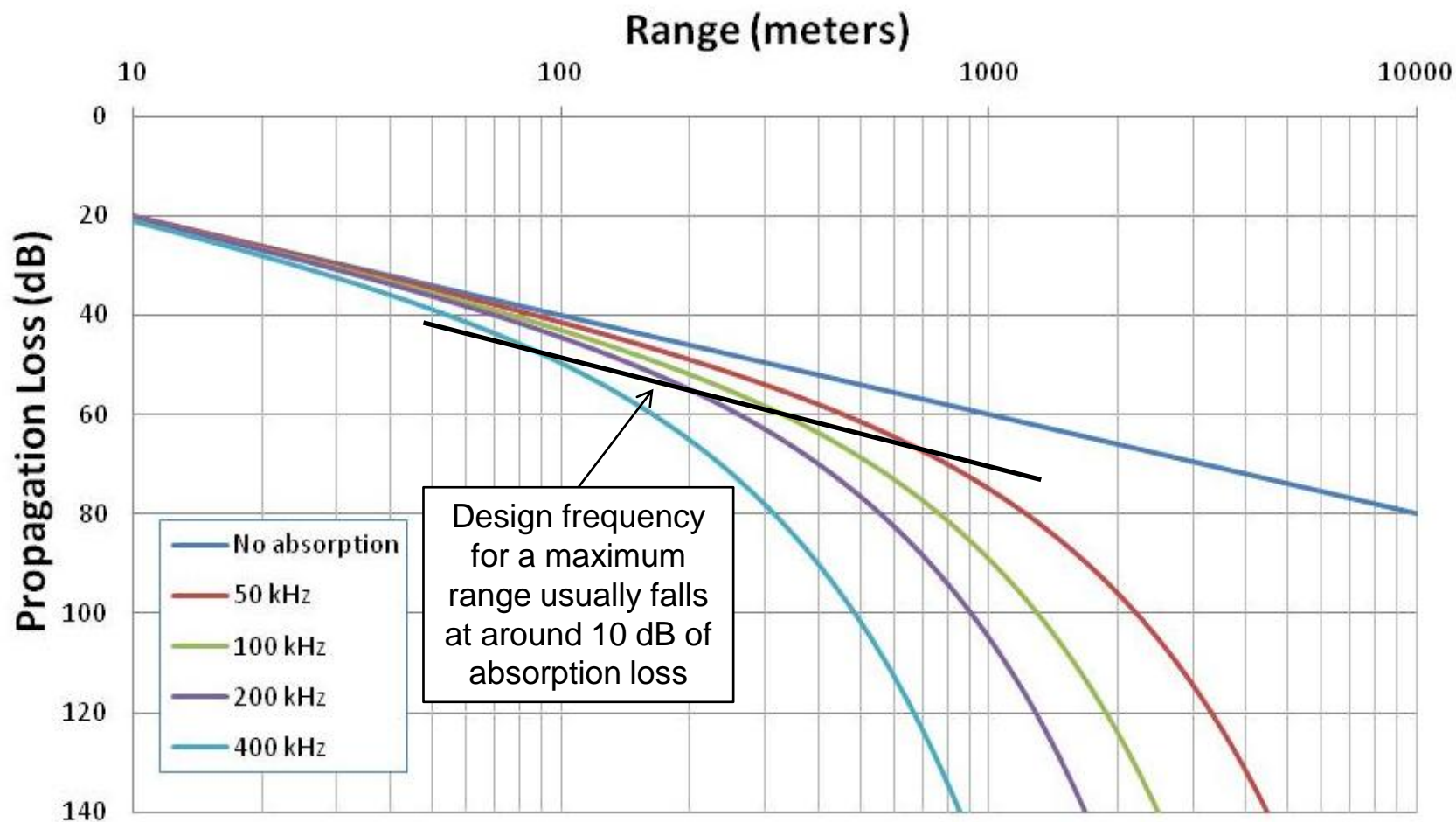


PART 1: Active acoustics: Why and why not?

- **Why?**
 - **If you really want/need to detect, localize, and track an underwater object active acoustics (i.e. active sonar) is the most robust method**
- **Why not?**
 - **The effects of the active acoustic transmissions on marine life**
 - **Systems often don't work that well for a variety of reasons**
 - **Systems that work well are generally very expensive and have limited coverage**

One-way propagation loss

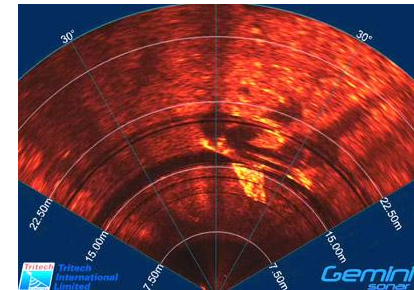
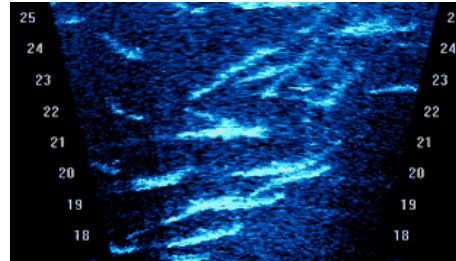
Propagation loss for different frequencies Spherical Spreading ($20 \log R + aR$)



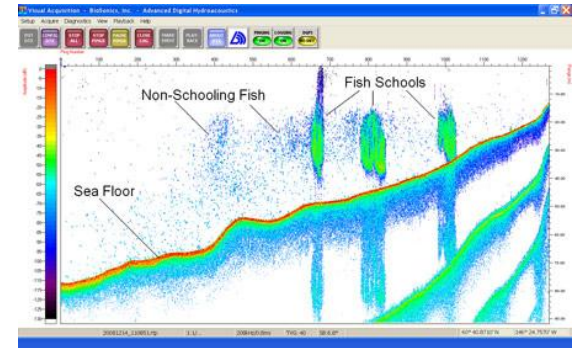
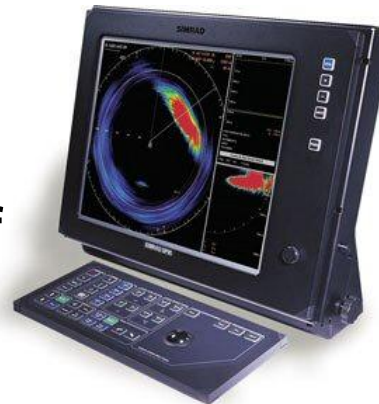
Common systems for bi-acoustic research

Different categories roughly depending on frequency

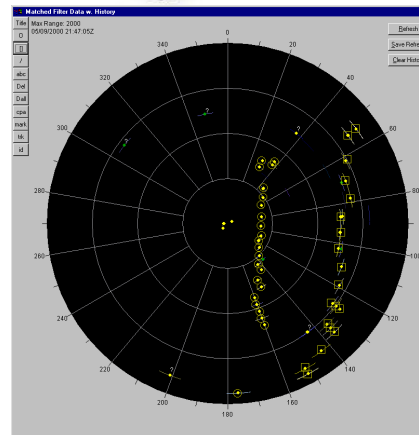
Imaging
Generally >400 kHz
Classification possible



Fish-finding
Generally 50-200 kHz
Location and estimation of
bio-mass possible



Longer range detection,
localization, and tracking
(30-100 kHz)
Robust classification not
there yet, bigger targets

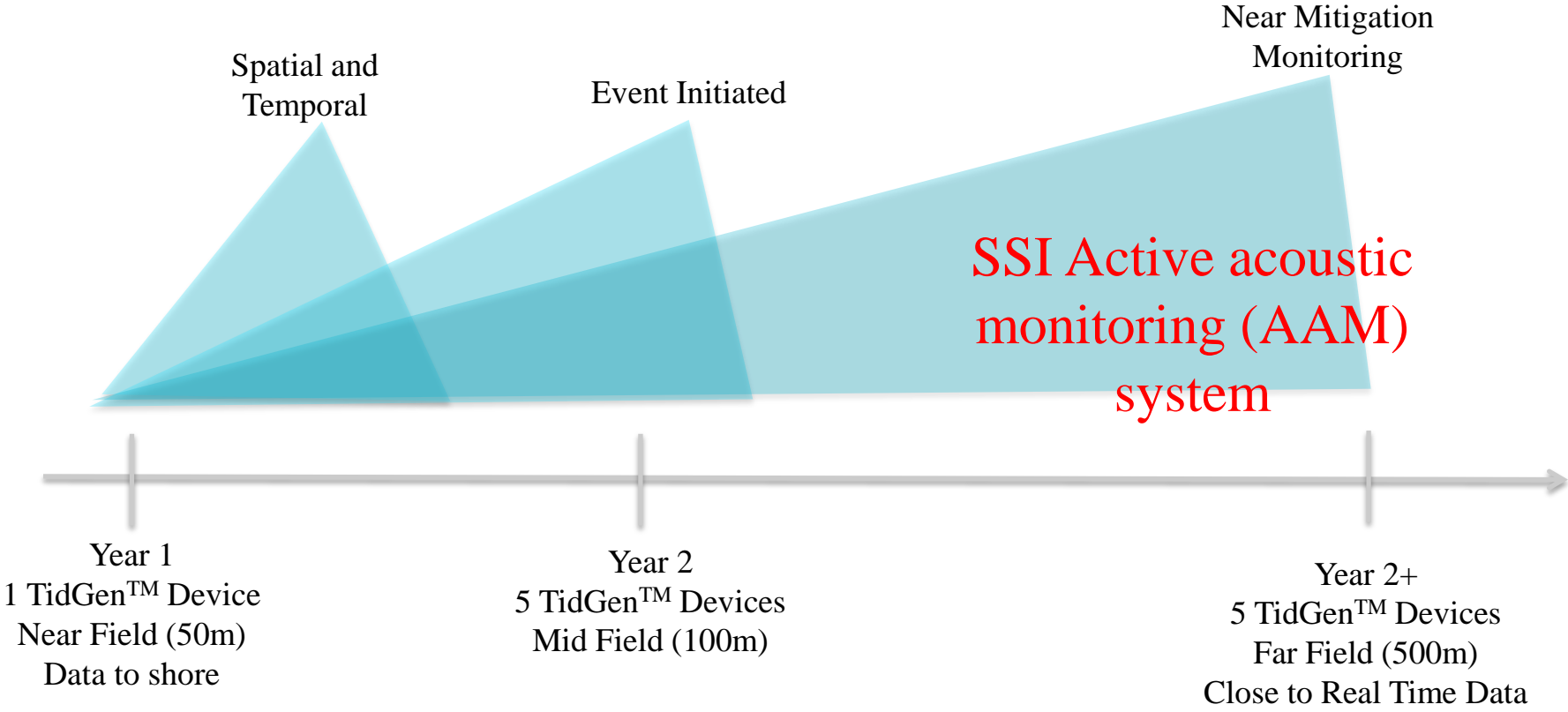


Evaluating and mitigating risks of marine hydroturbines



TidGen™ unit being installed off Eastport, Maine by the Ocean Renewable Power Company (ORPC)

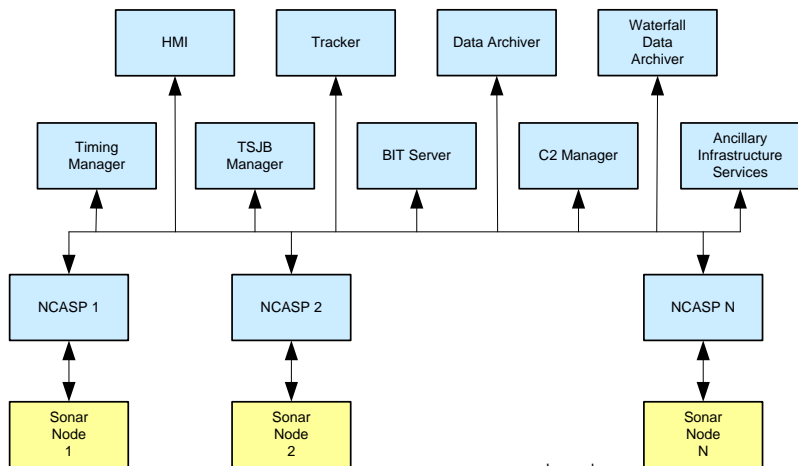
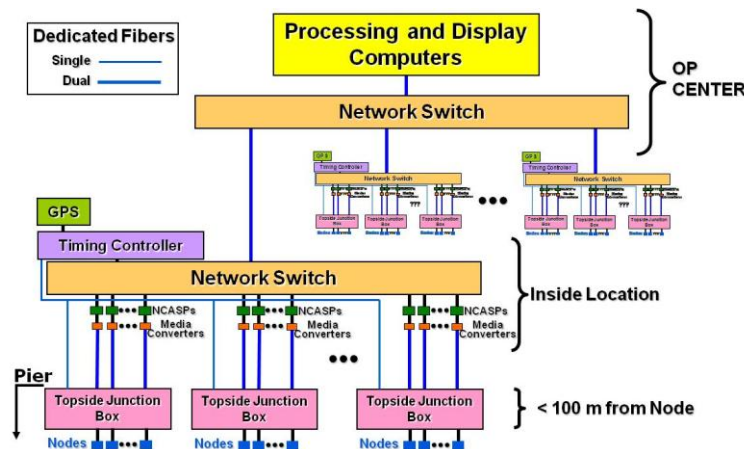
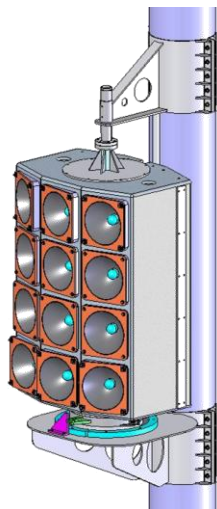
Plan: Integrated Near-field and Far-Field Systems



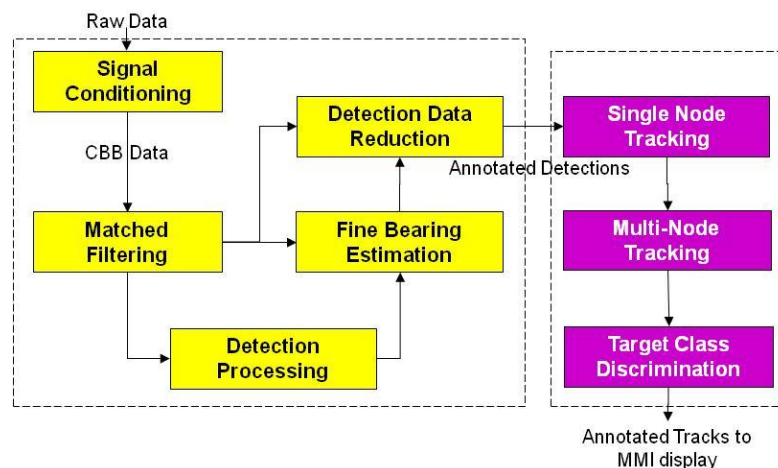
Swimmer detection systems as a basis for AAM

- **An effective AAM for offshore renewable energy applications has pretty much the same requirements as swimmer detection sonar**
 - **Automatic detection, tracking, localization, and classification of low target strength objects in a shallow water harbor environment**
- **Swimmer detection sonar systems are fairly well developed, however most are very expensive and classification is still an issue**
- **SSI has been working since 2002 to develop a cost effective swimmer detection sonar system based on networking simple inexpensive sonar “nodes”**
- **The SSI/ORPC AAM program is based on leveraging the on-going SDSN development**

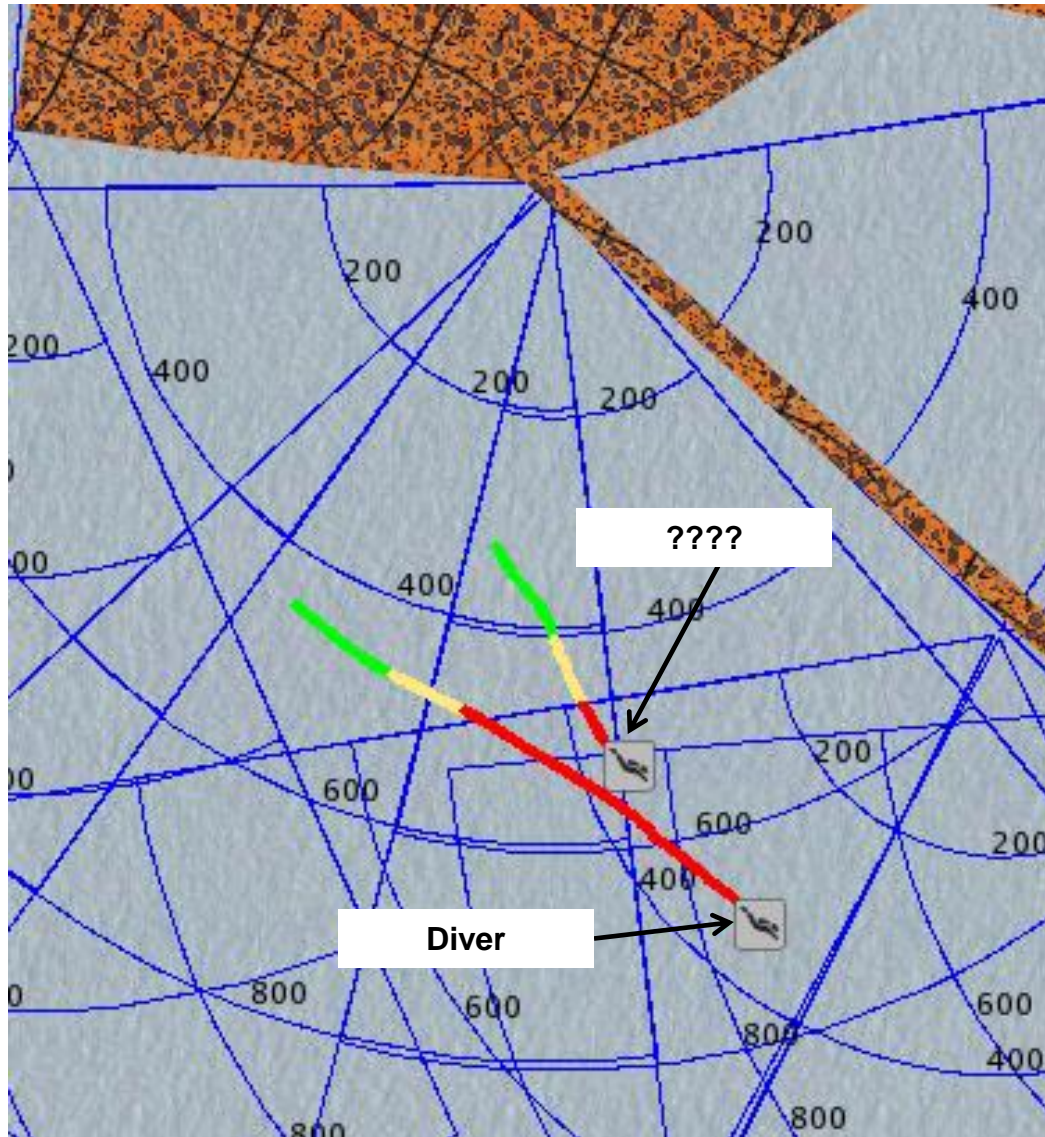
Swimmer Detection Sonar Network (SDSN)



Legend:
 HDS API Enabled Hardware
 Other Hardware



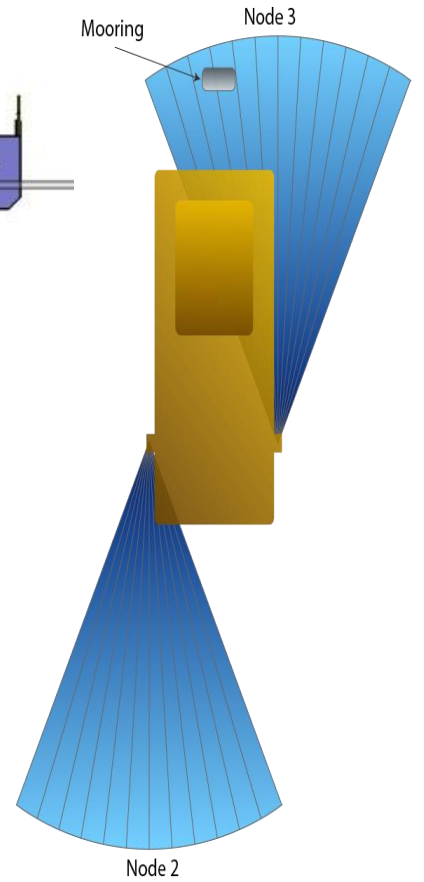
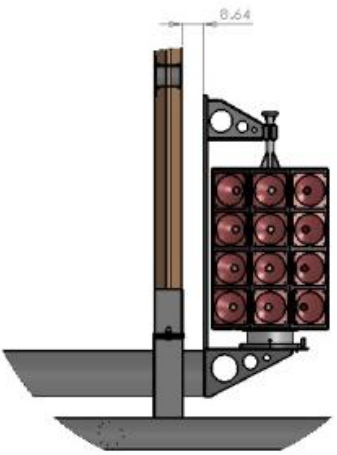
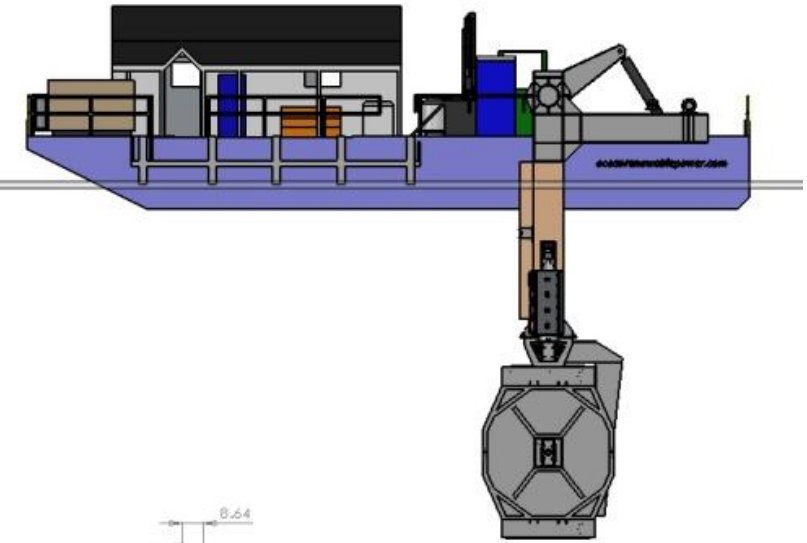
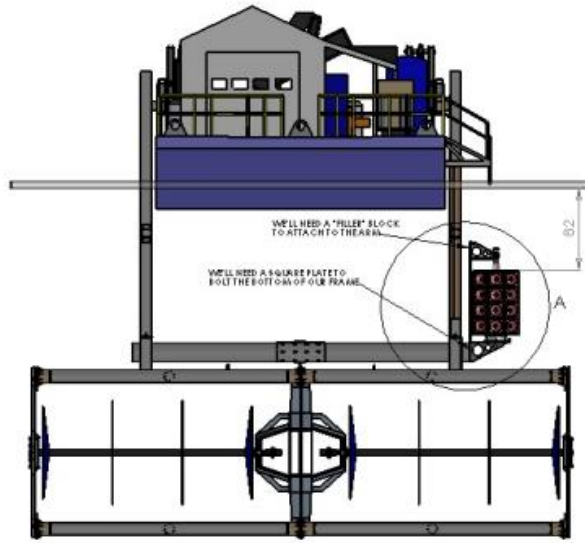
Recent Trial Results



Major uncertainties

- **Will longer range detection, localization, and tracking systems work in the required environment?**
 - **High currents?**
 - **Variable sound speed field?**
 - **Potentially rocky bottom?**
- **That is, will it work off Eastport, Maine?**

Test installation using existing nodes and ORPC beta



Eastport Testing of Current Node – September 2010

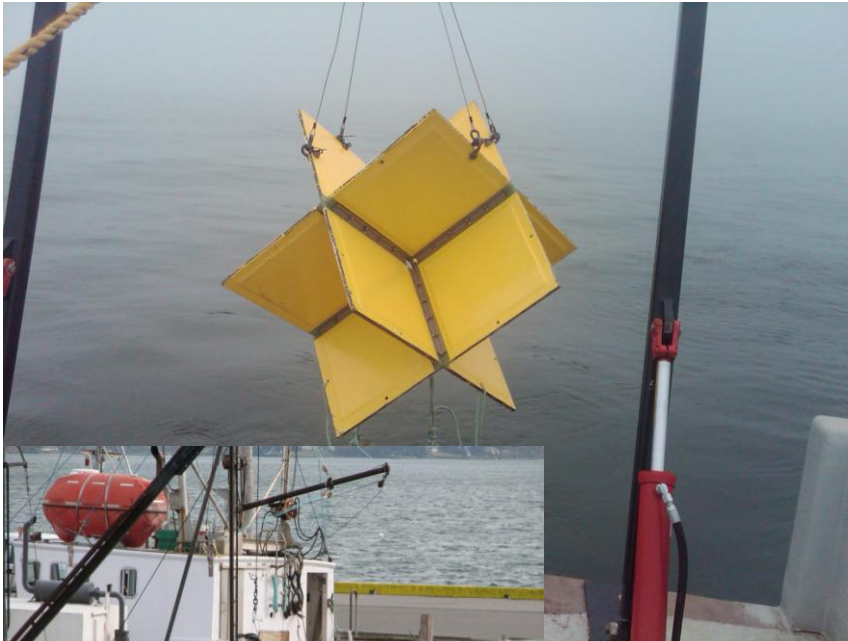


Eastport Drift/Tow Tests

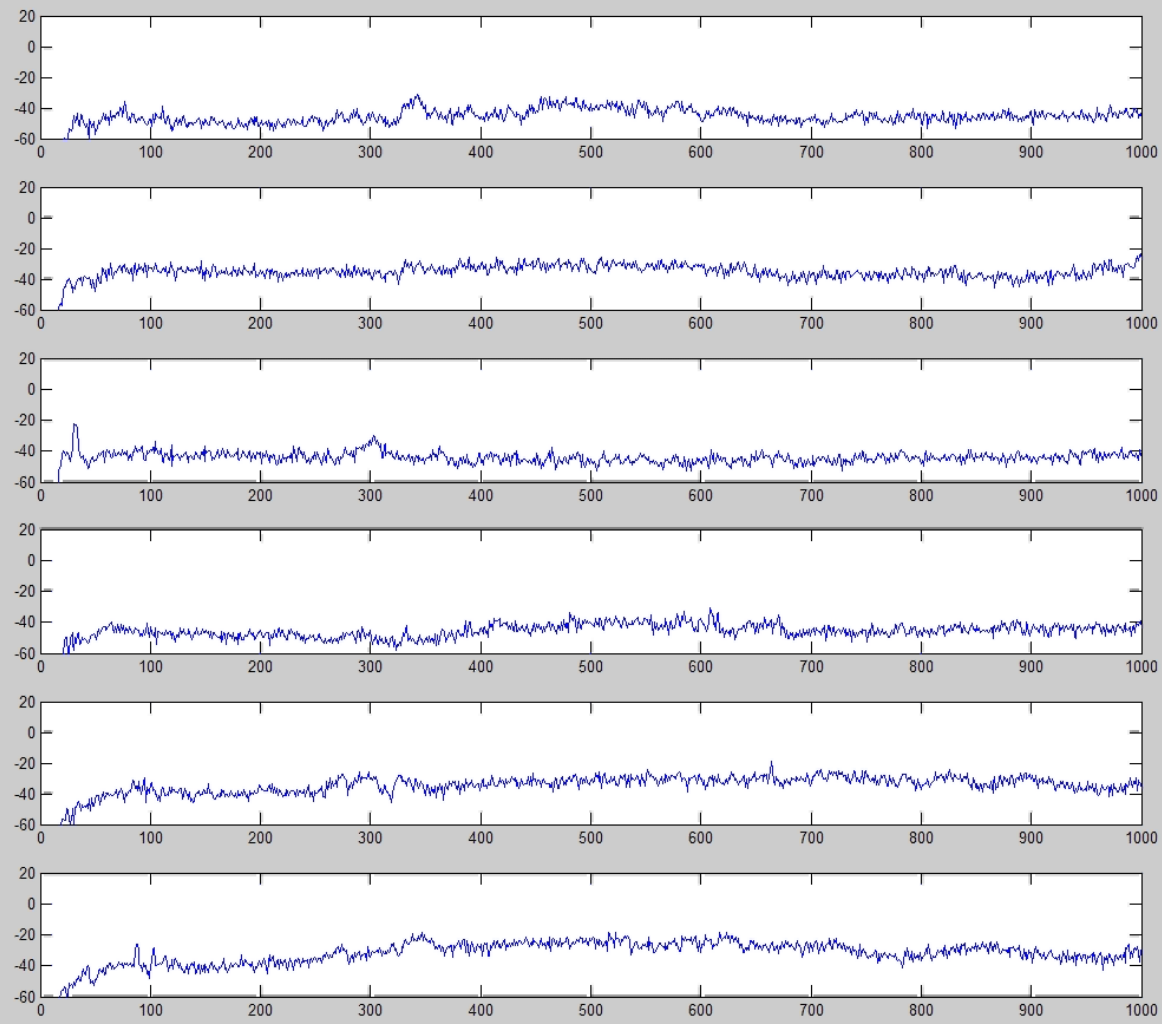
➤ **Two targets:**

➤ **TS = -5 to +5 dB re 1 m (mid-size whale)**

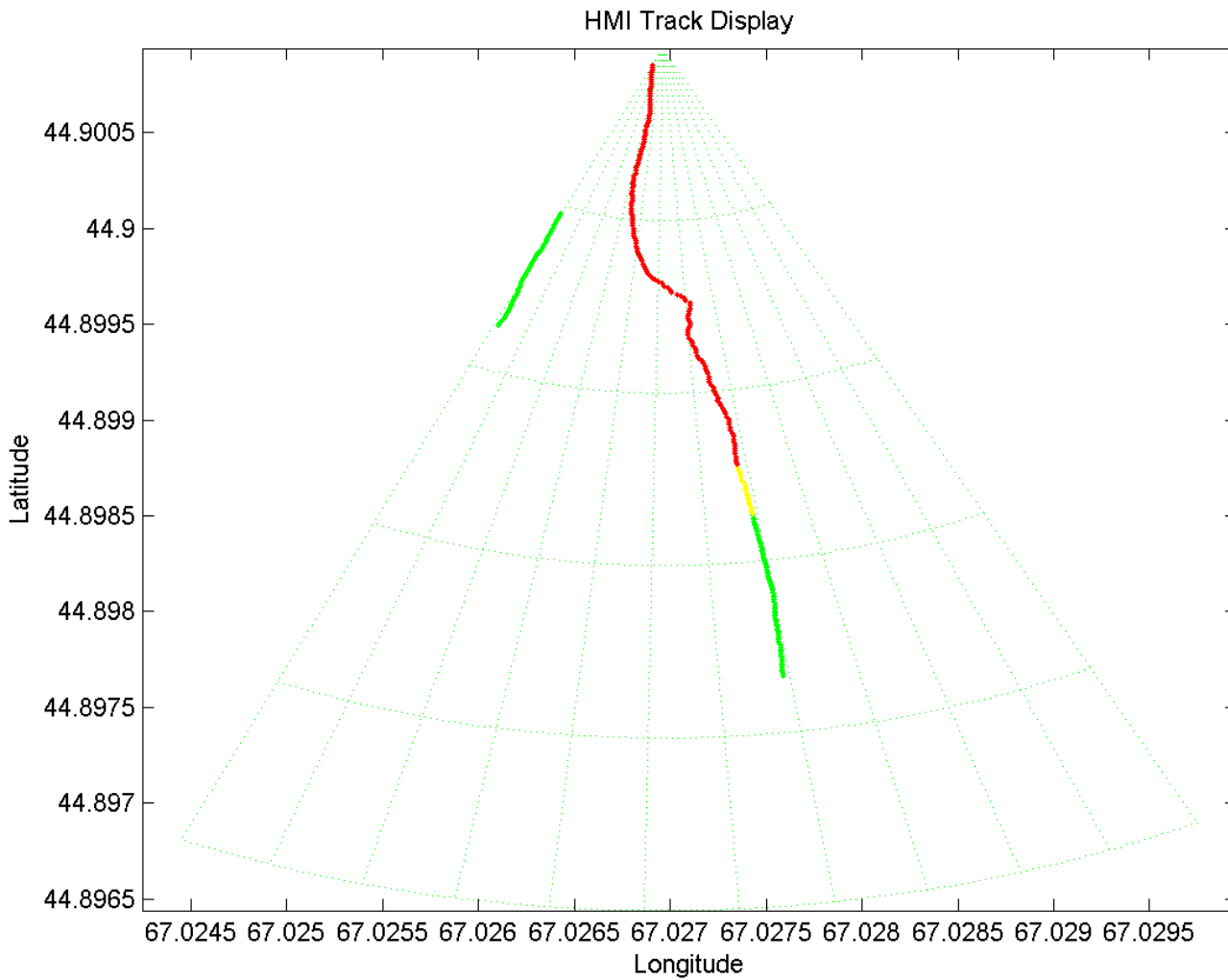
➤ **TS = -20 to -15 dB sphere (small odonocete/pinneped)**



Large target run



Small target tracker results



New Node

45-75 kHz Assembly

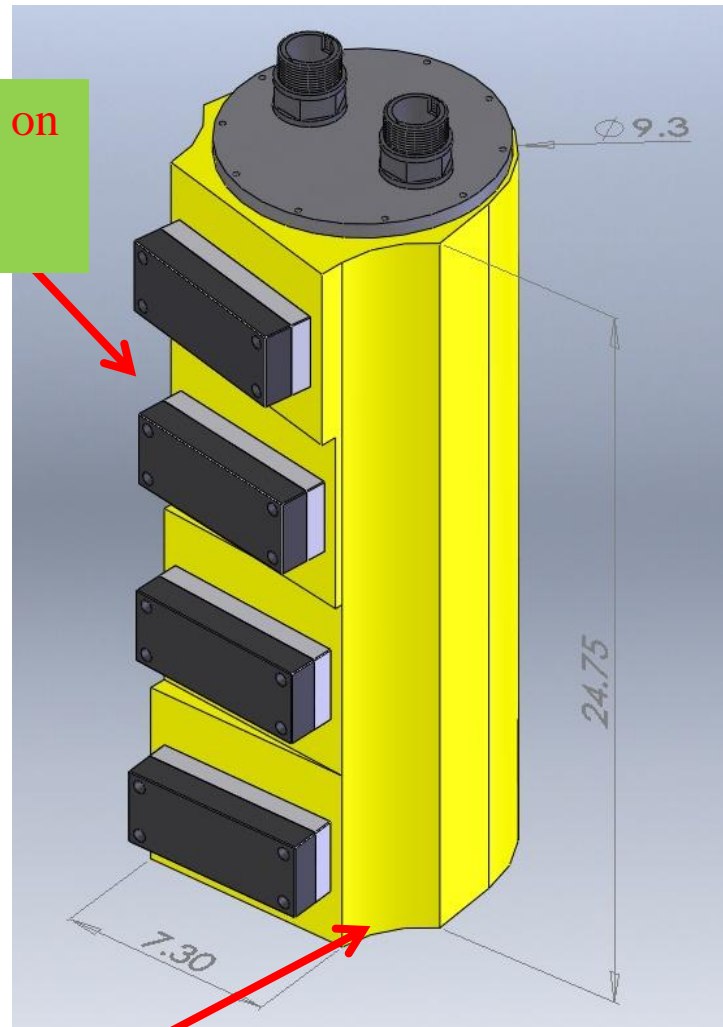


HF Transducers on
Electronics
Enclosure

LF Transducers

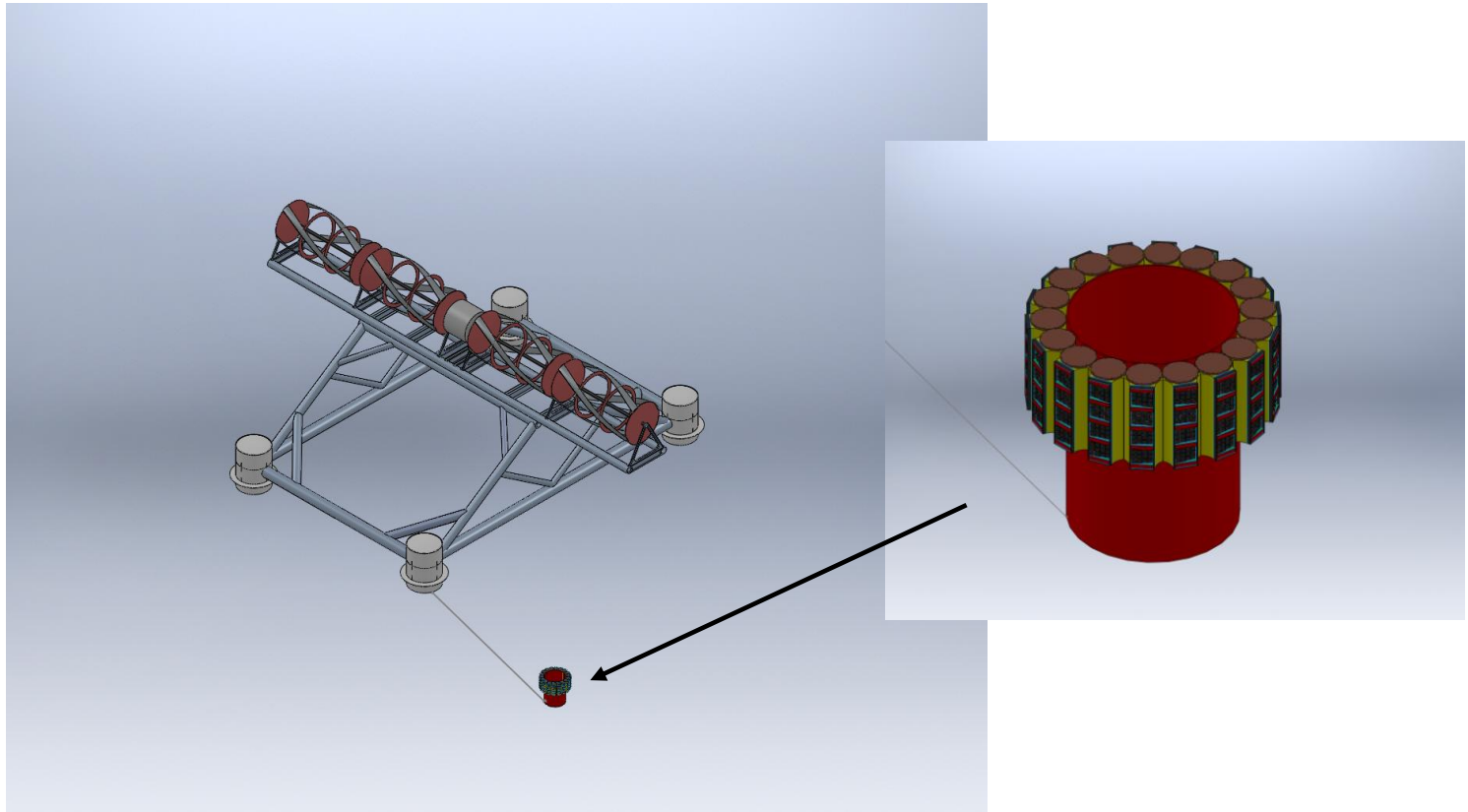
Electronics

90-120 kHz Assembly



AAM Installation on (near?) ORPC TidGen™ Unit

SSI is now teamed with ORPC to develop AAM for marine hydrokinetic energy applications



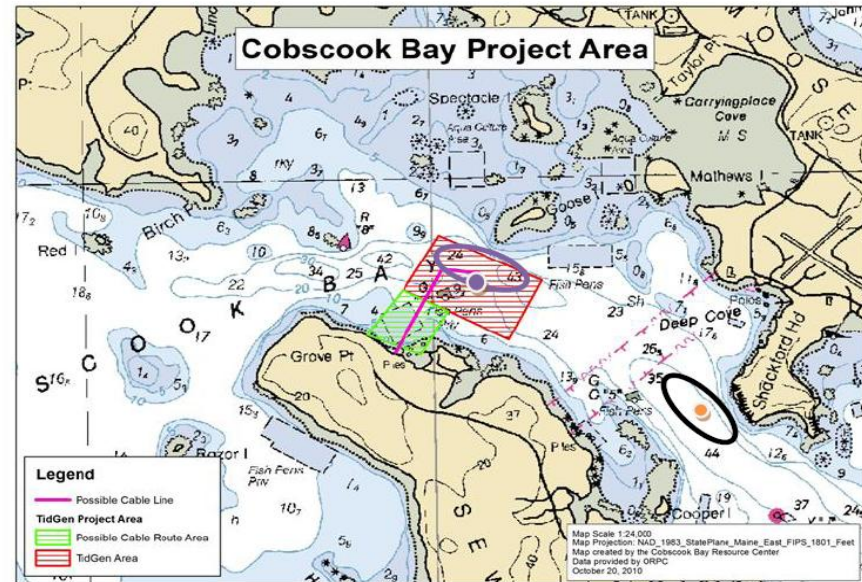
Conclusions (AAM)

- **There are many active acoustic systems available for mitigation and monitoring**
 - **Generally high frequency imaging systems and thus limited coverage for the cost**
- **There is one operational system (I know of) for longer range DLTC of marine mammals (SURTASS LFA HF/M3 Sonar)**
- **AAM systems are under development which may eventually lead to robust longer-range DLTC of marine mammals and fish (classification will always be difficult)**
- **Integration of systems will lead to greatest advancements**
- **Issues related to marine mammal harassment need to be studied and evaluated**

PART 2: Radiated Noise Measurements In High Currents

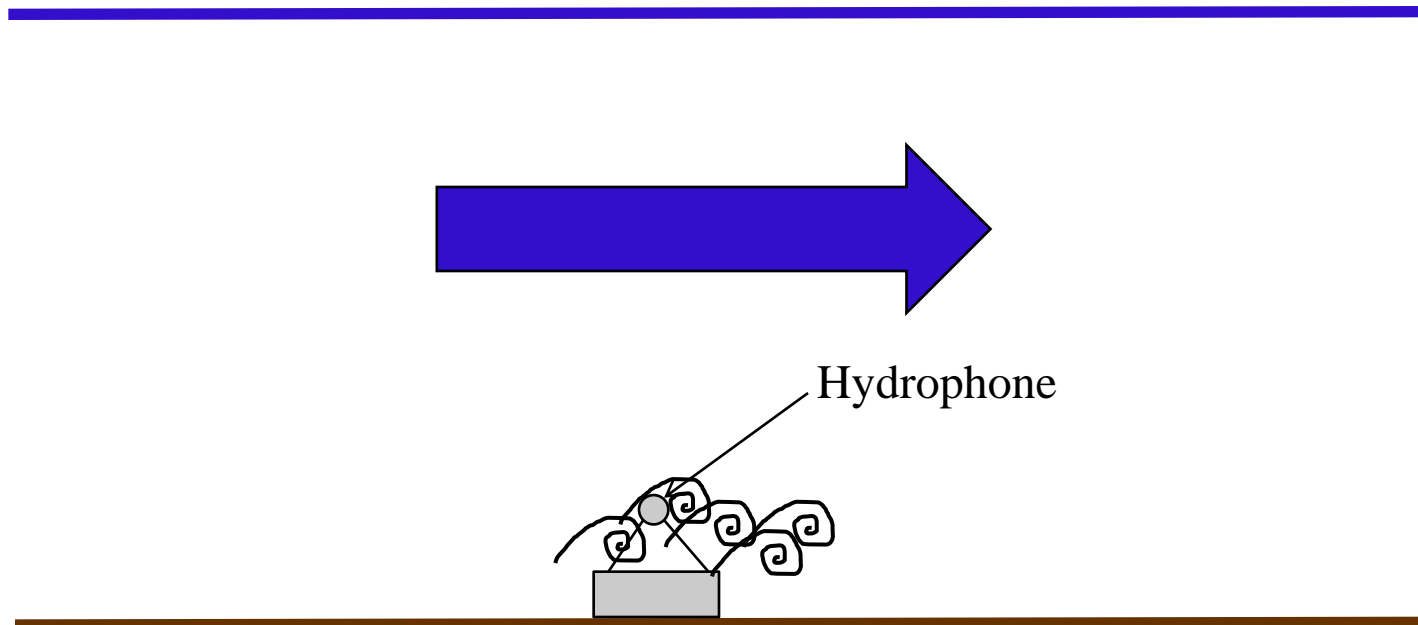
Need to determine radiated noise impacts of tidal turbines

However, high currents make accurate noise measurements very difficult



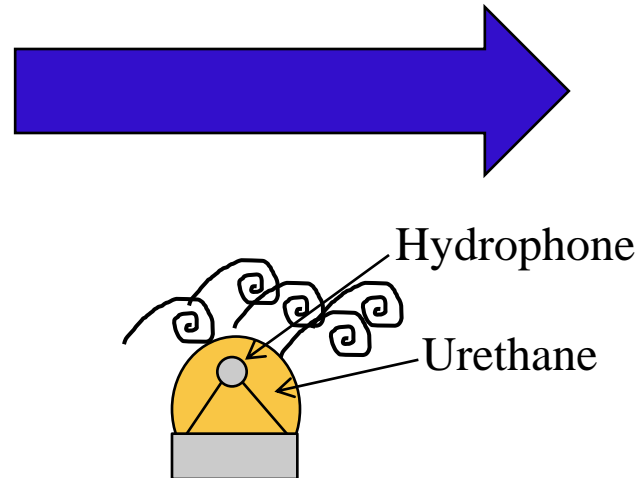
- CB1 (circled in purple)
- CB2 (circled in black)
- Beta barge location Feb – Jul 2010 (orange dot)
- Beta barge location Aug – Dec 2010 (purple dot)

Will be contaminated by turbulent flow noise



Turbulent fluctuations stay away from hydrophone

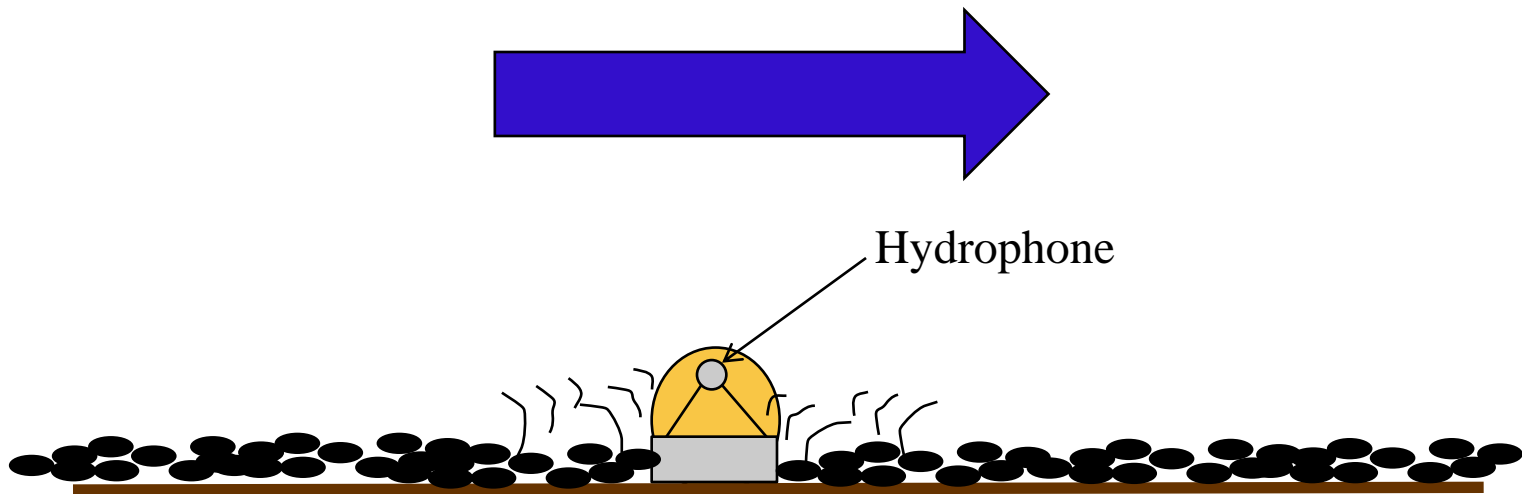
- But calibration gets very tricky due to added frequency dependence
 - Low frequency turbulence still gets through
 - High frequency sound of interest can get absorbed by urethane
-



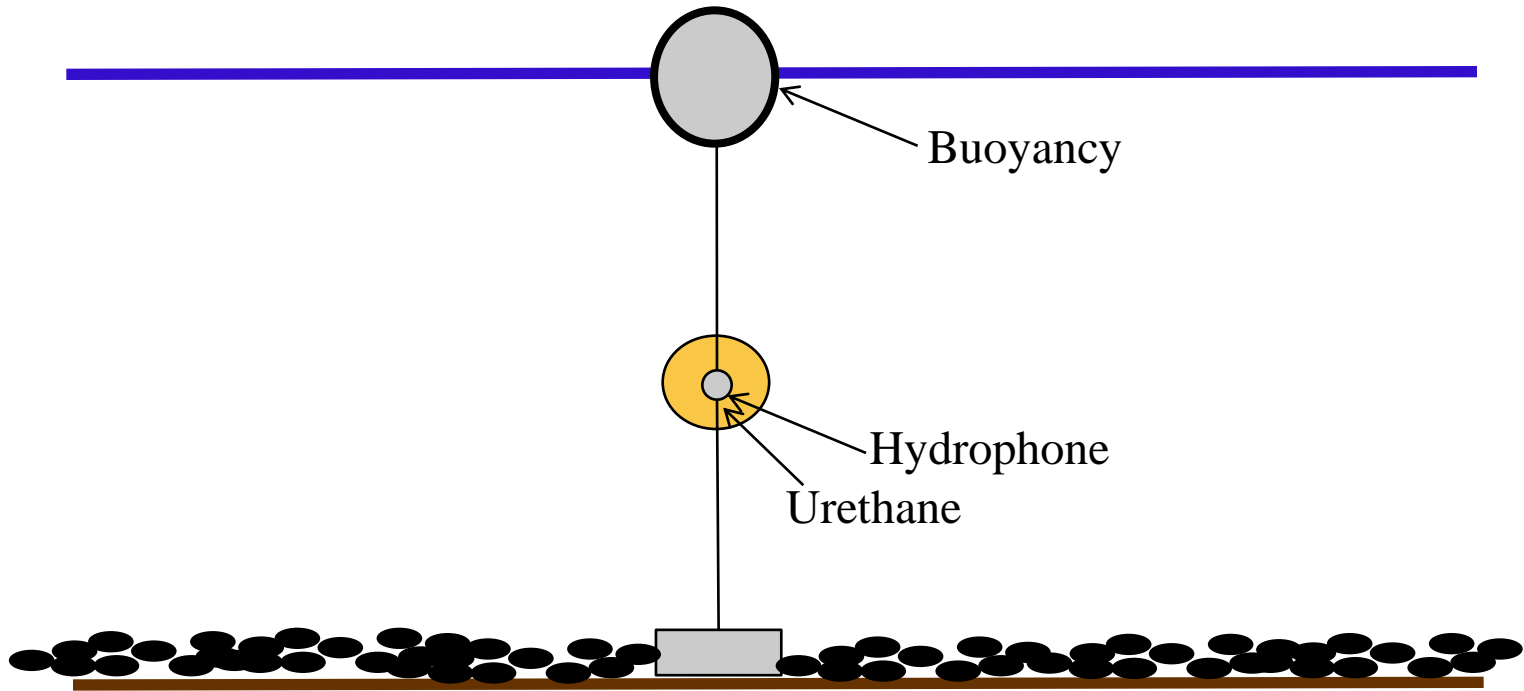
Further: Moored system subject to contamination

Local bottom noise sources dominate

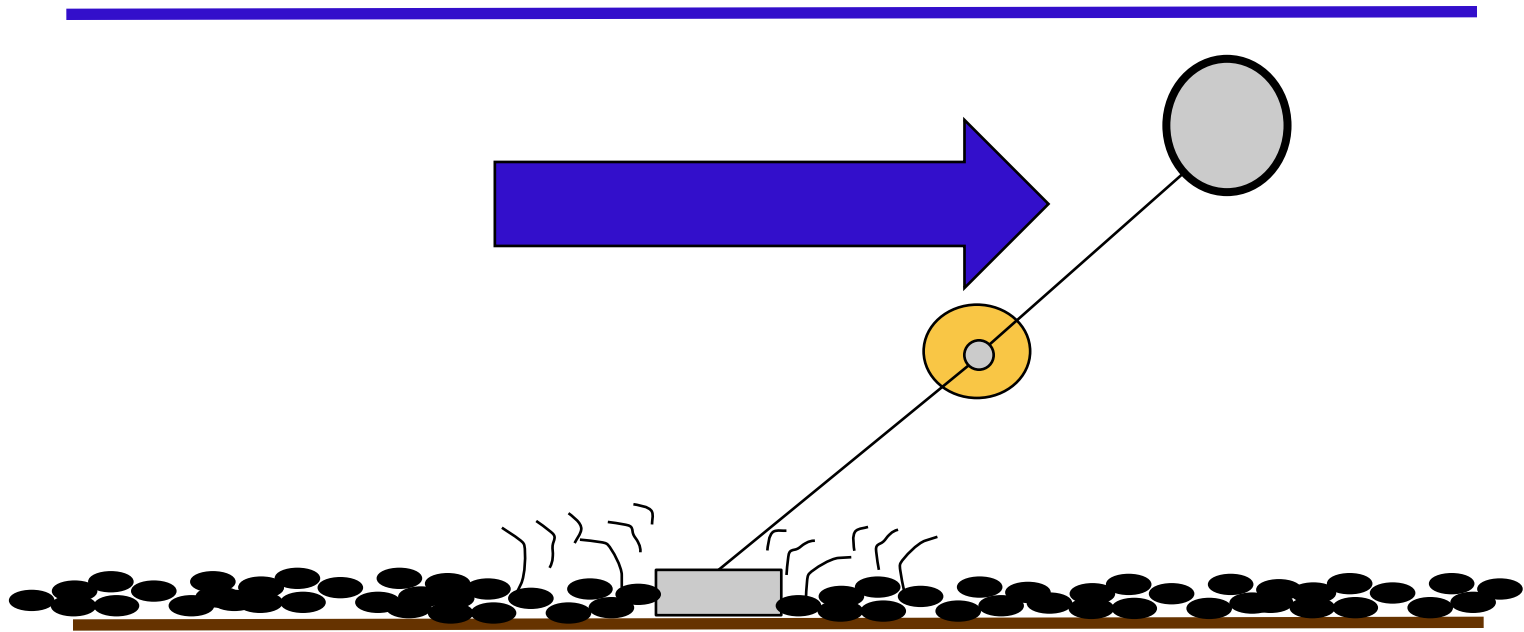
- **i.e. noise is depth dependent**



Maybe suspend hydrophone in water column

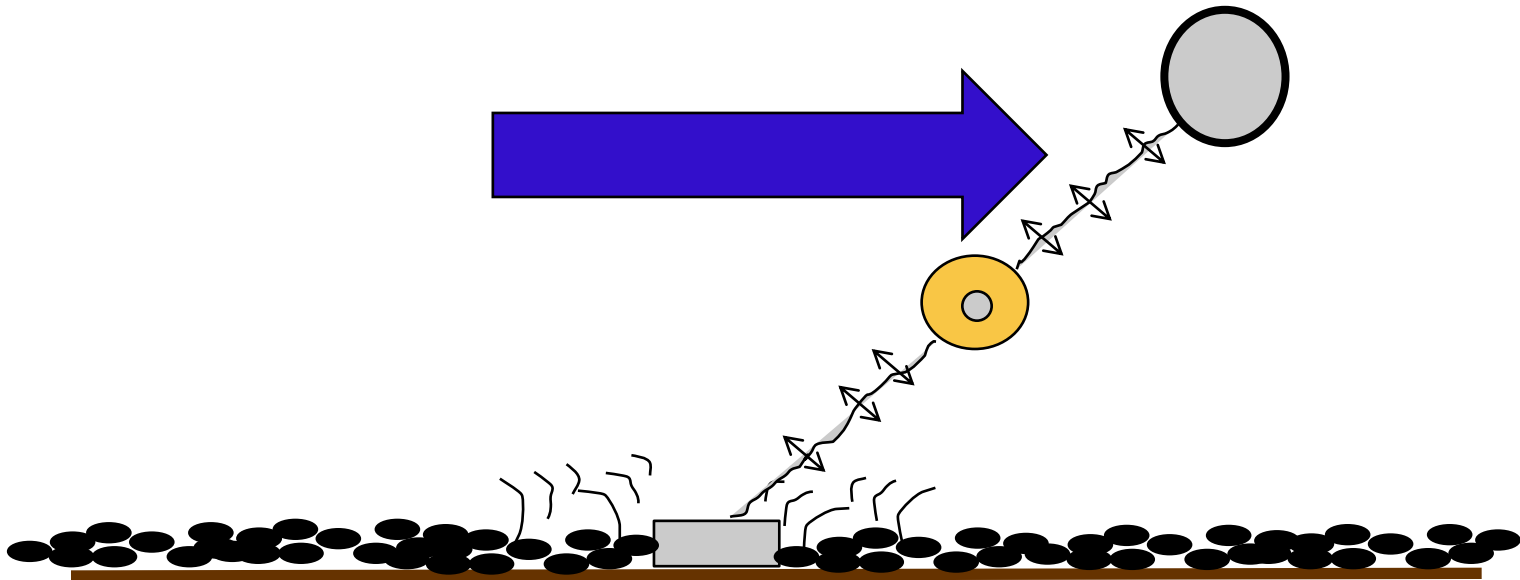


Besides getting a little scary



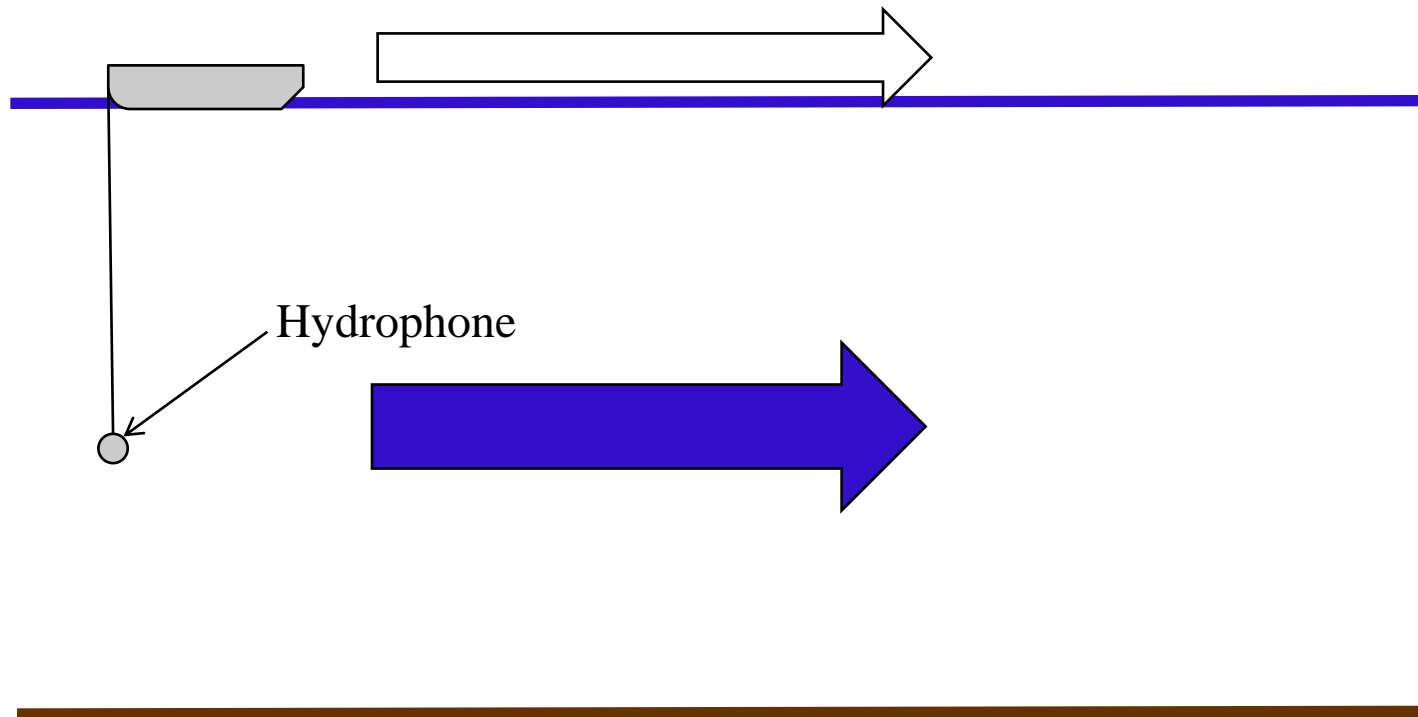
There is also cable strum

- **Violent shaking of the cable**
- **Noisy (shaking of hydrophone, couplings)**
- **Change in depth due to cable shortening and lengthening can lead to pressure fluctuations usually enough to saturate preamplifiers**

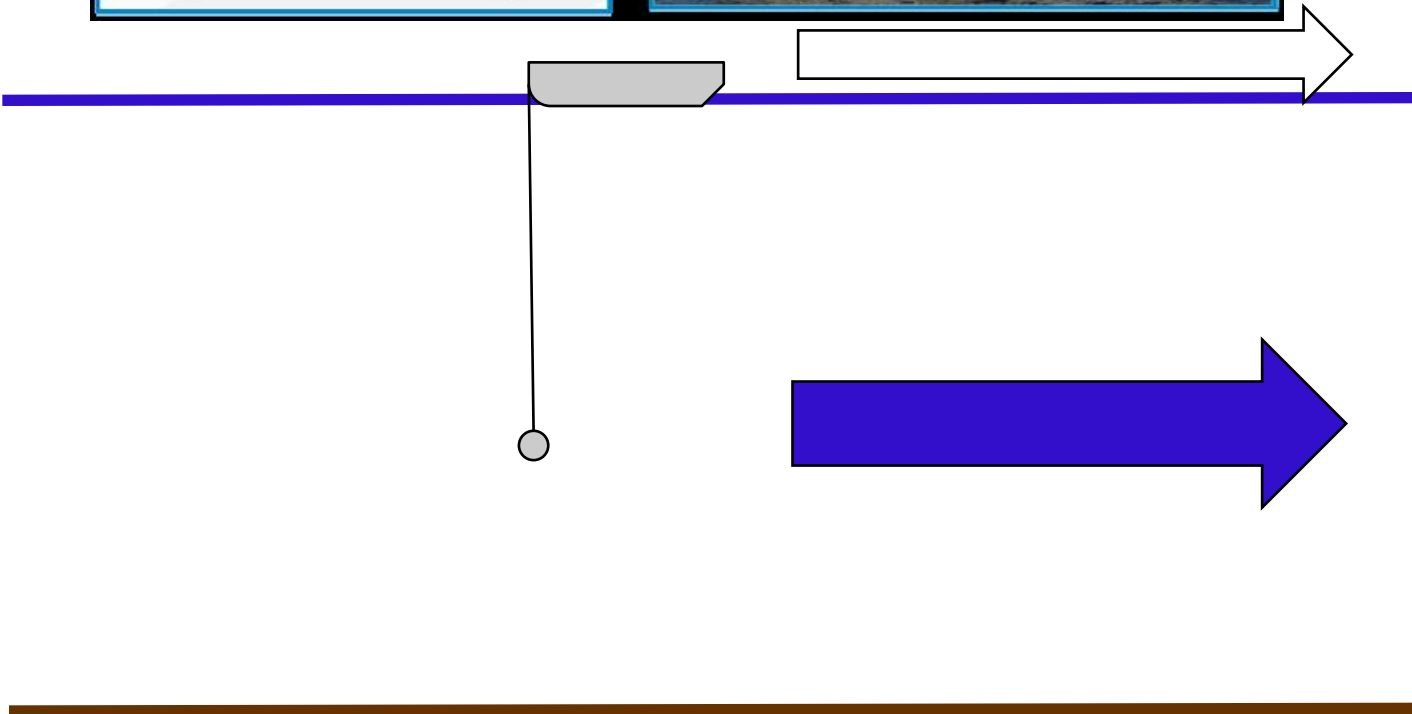
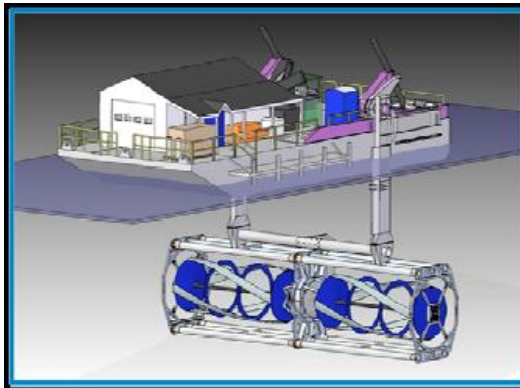


Solution

- Suspend hydrophone from a drifting platform
- Drift with and without the tidal generator in the path

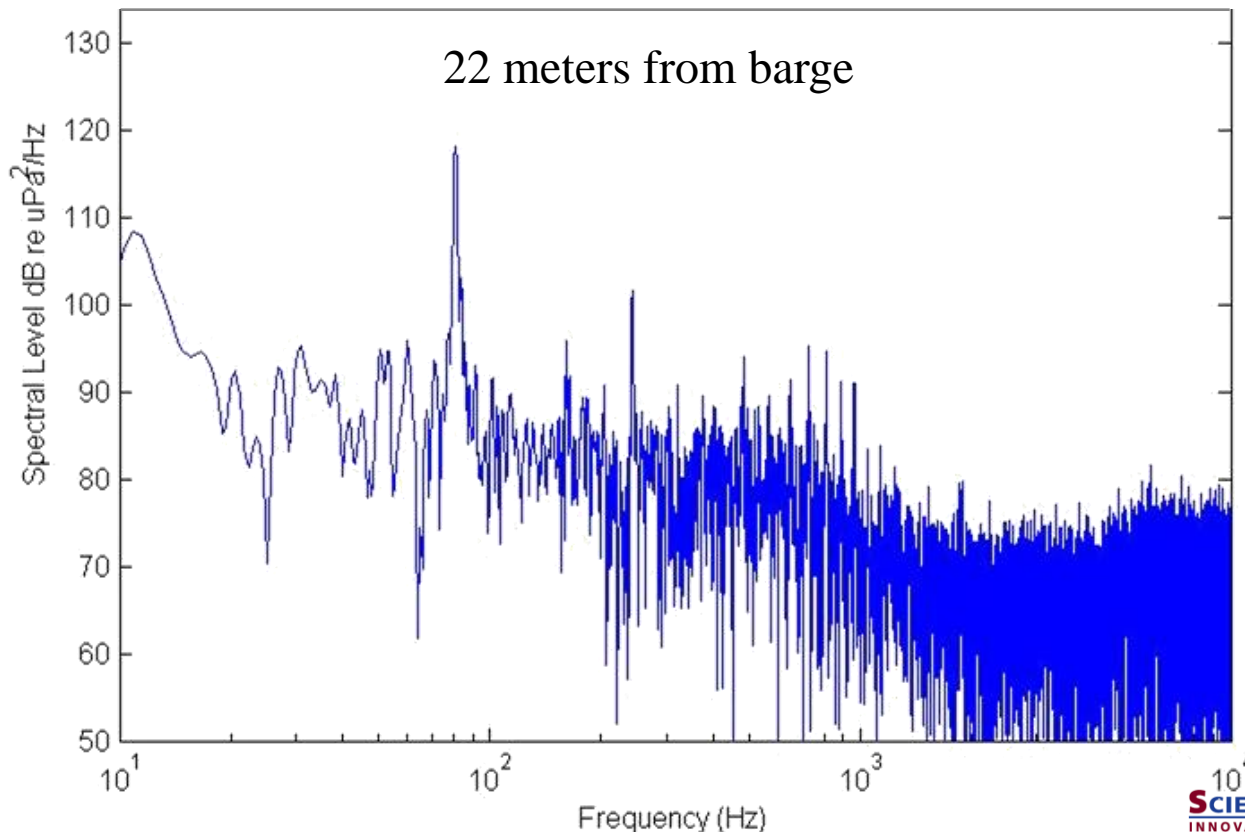


Feasibility test conducted last fall

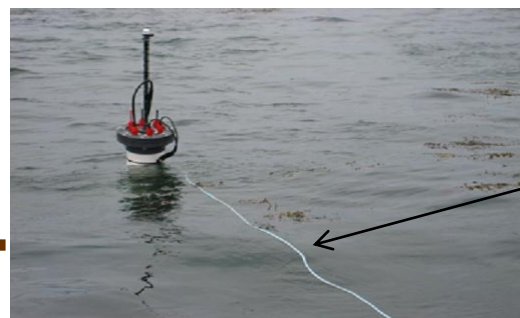
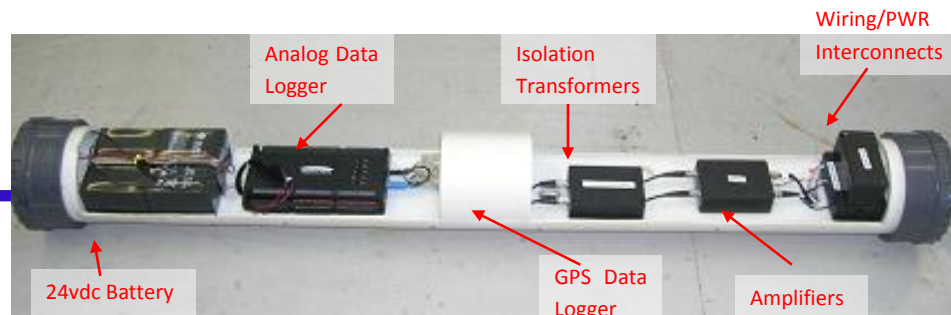
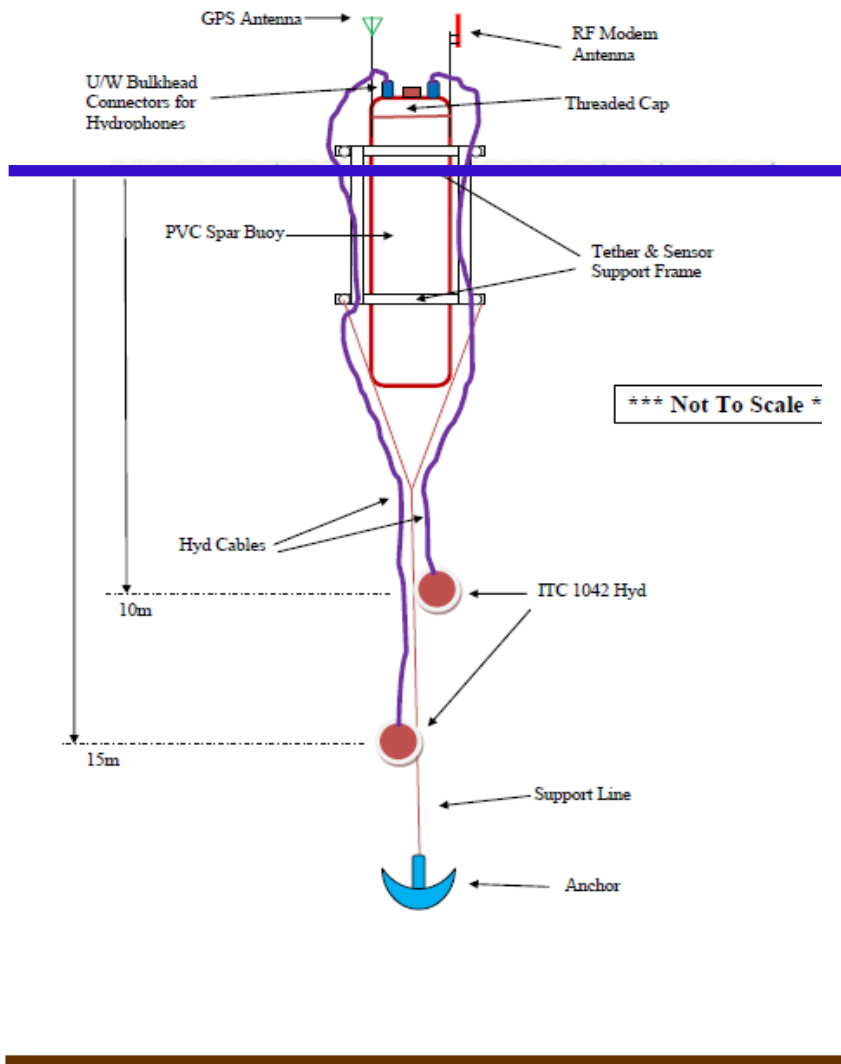


Data: Hydrophone suspended from drifting platform

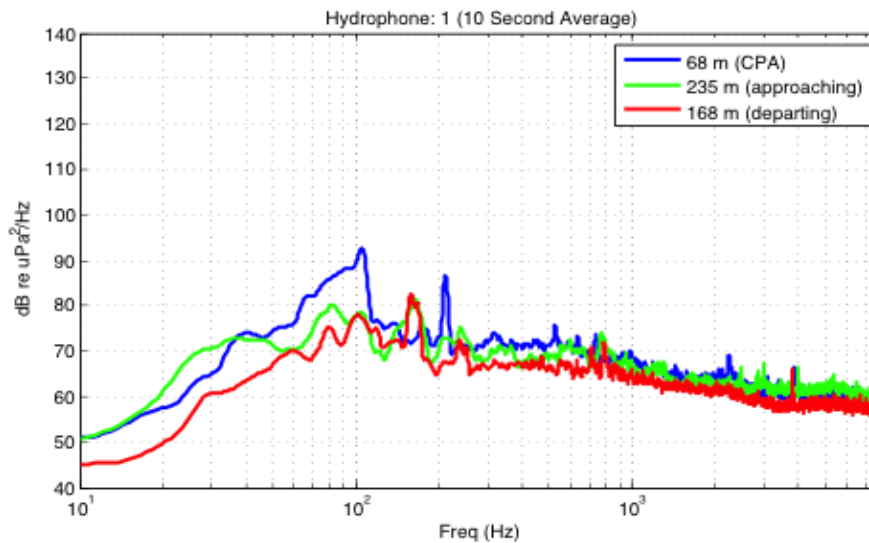
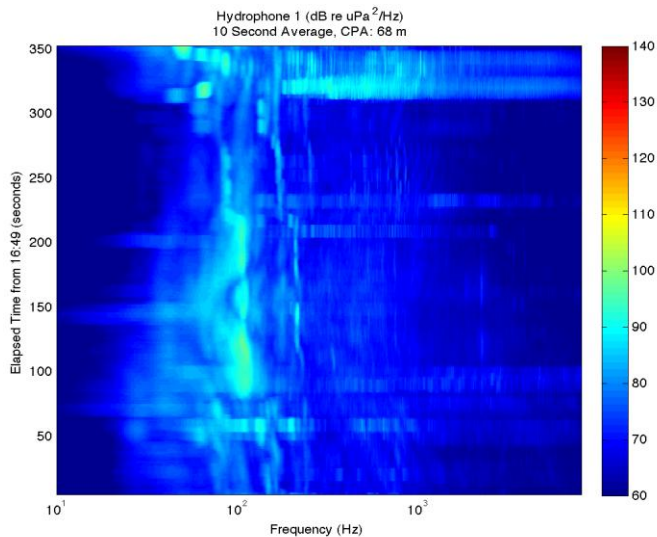
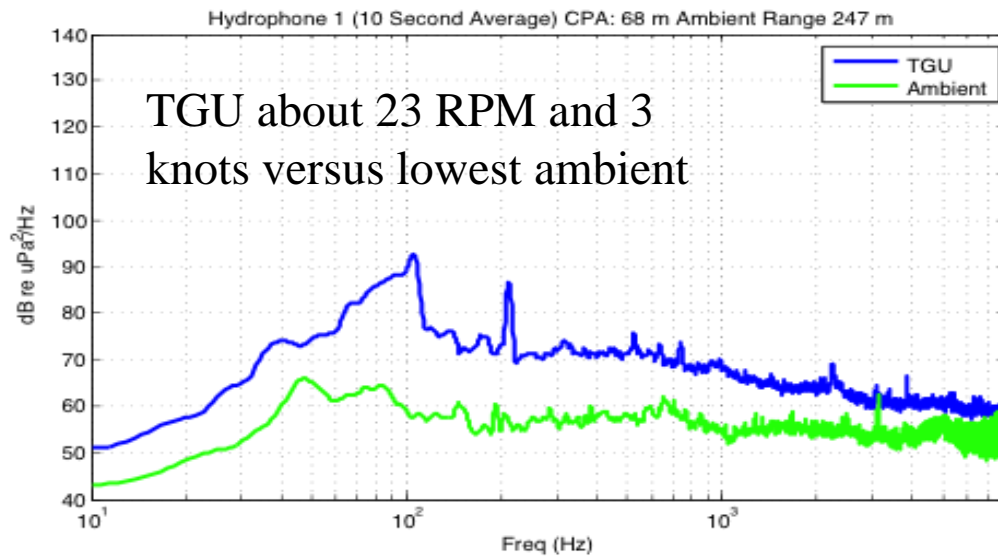
- Very promising, but data still contaminated
- Boat rocking caused noise and hydrophone heave
- Some cable strum due to some differential motion between boat and current (wind also drives the boat)
- A lot of sifting to get even small chunks of good data



Designed and built spar buoy to remove last issues



Tests with spar buoy conducted in July



Conclusions

- **High current noise measurements can be made from a drifting spar buoy**
- **It is very labor intensive and not feasible for continuous long-term monitoring**
- **OPRC turbine is very quiet**
 - **No incidental harassment authorization (IHA) required**
- **Plan for tidal generator is to install accelerometers on the unit**
 - **Radiate noise will be correlated with accelerations**
 - **Accelerometers will then provide long-term monitoring of noise levels (also failure detection)**