

Extending the Scope of Algebraic MINLP Solvers to Black- and Grey-box Optimization

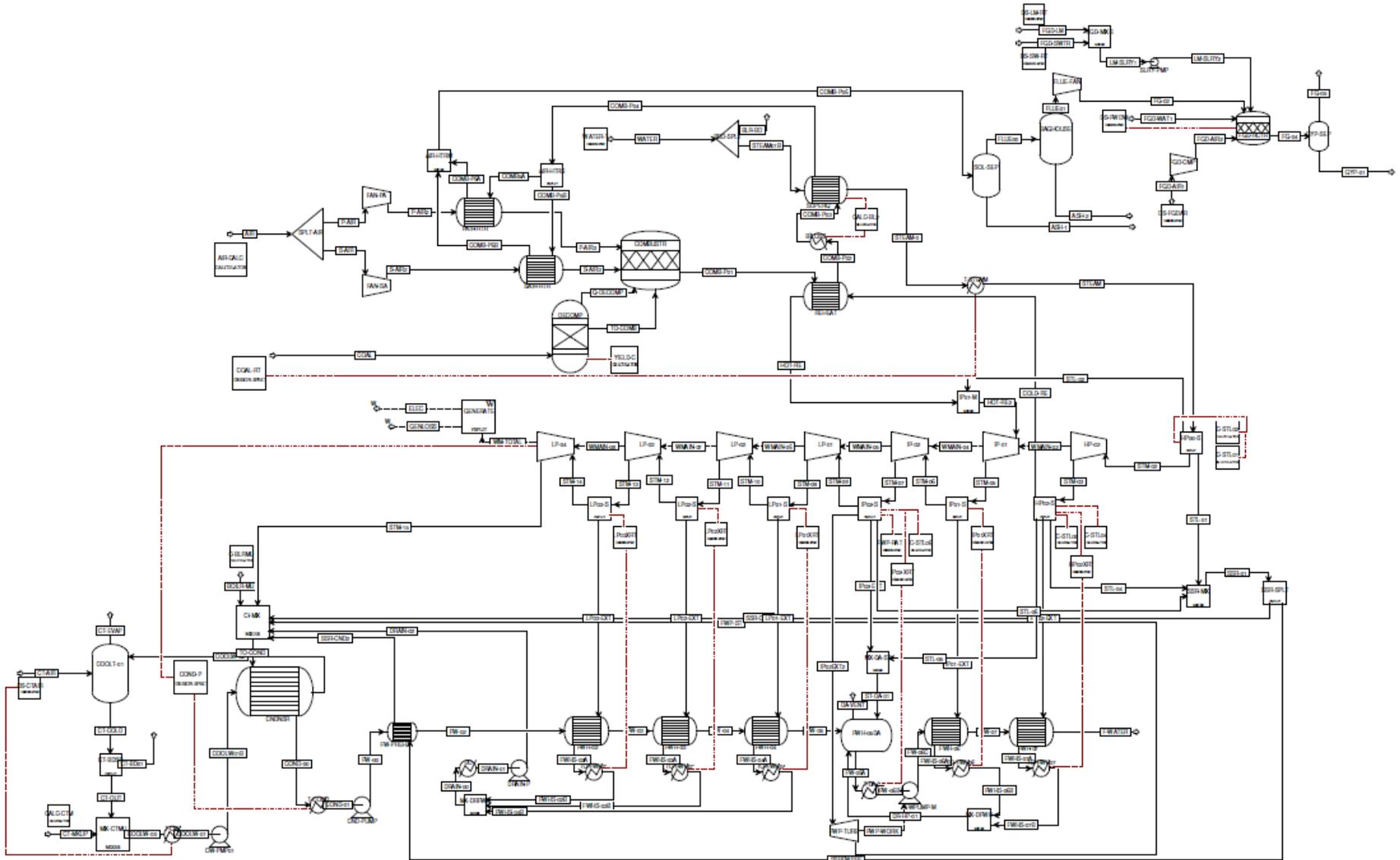
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Acknowledgments:

Alison Cozad, David Miller, Zach Wilson

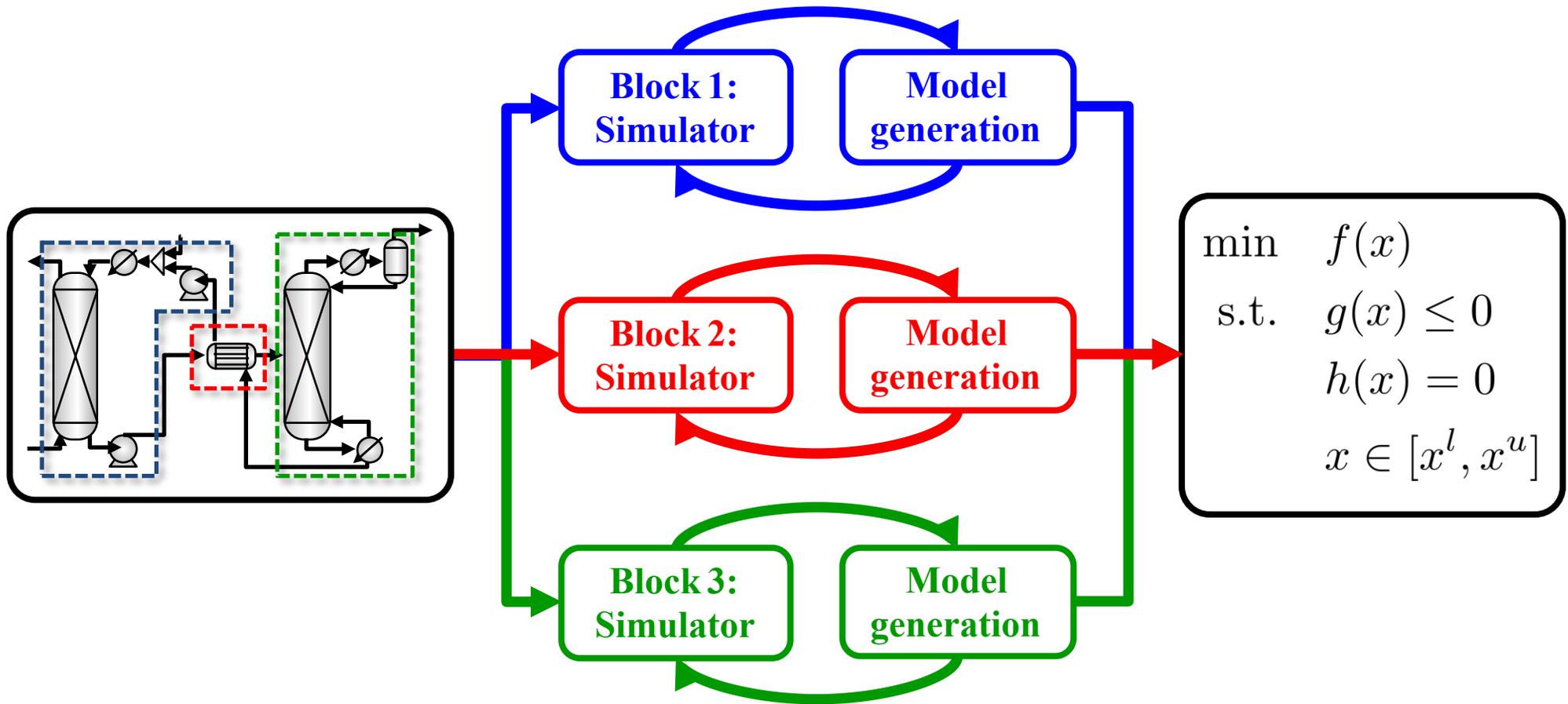


SIMULATION OPTIMIZATION



Pulverized coal plant Aspen Plus® simulation provided by the National Energy Technology Laboratory

PROCESS DISAGGREGATION



Process Simulation

Disaggregate process into process **blocks**

Surrogate Models

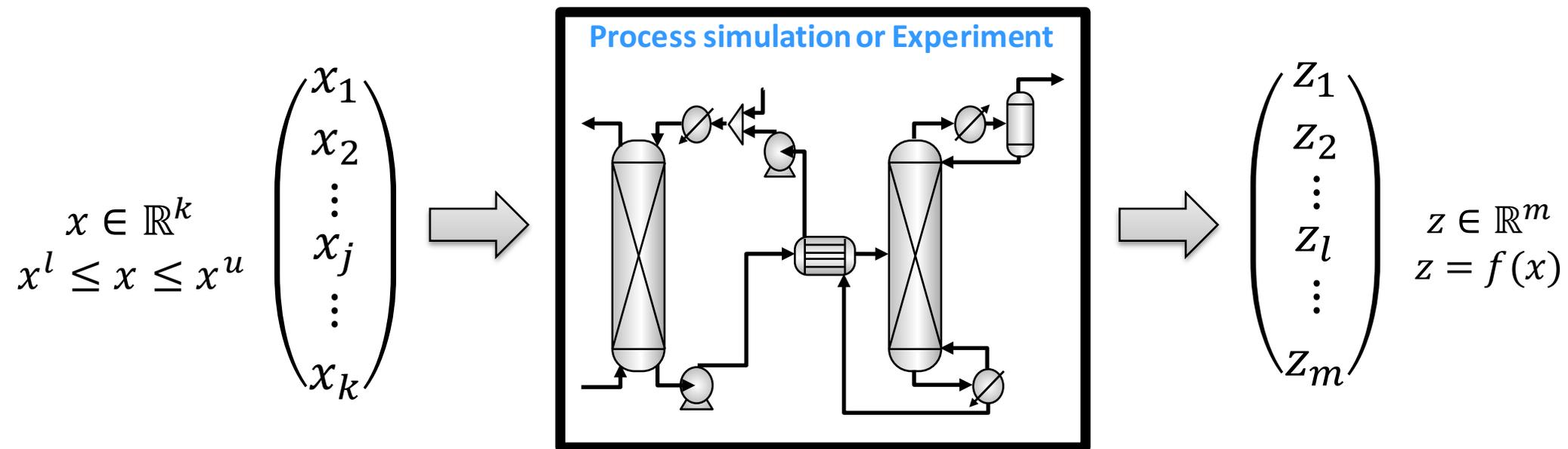
Build **simple** and **accurate** models with a functional form tailored for an optimization framework

Optimization Model

Add algebraic constraints design specs, heat/mass balances, and logic constraints

LEARNING PROBLEM

Build a model of output variables z as a function of input variables x over a specified interval

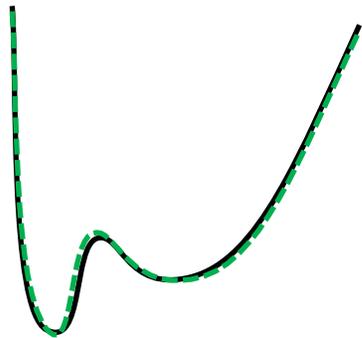


Independent variables:
Operating conditions, inlet flow
properties, unit geometry

Dependent variables:
Efficiency, outlet flow conditions,
conversions, heat flow, etc.

HOW TO BUILD THE SURROGATES

- We aim to build surrogate models that are
 - Accurate
 - *We want to reflect the true nature of the simulation*
 - Simple
 - *Tailored for algebraic optimization*



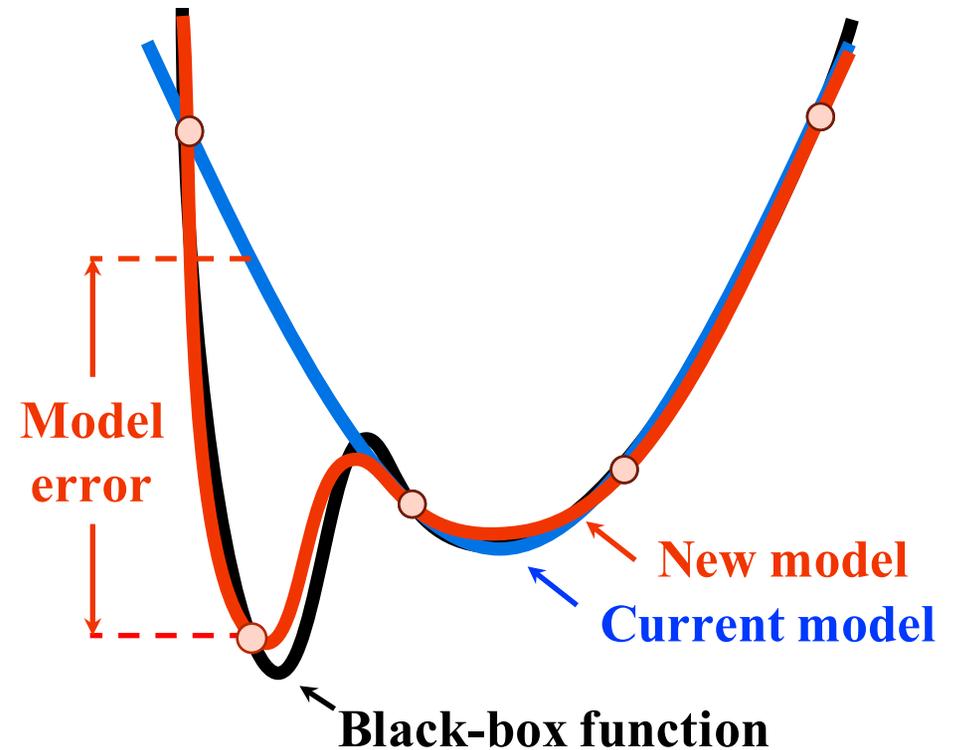
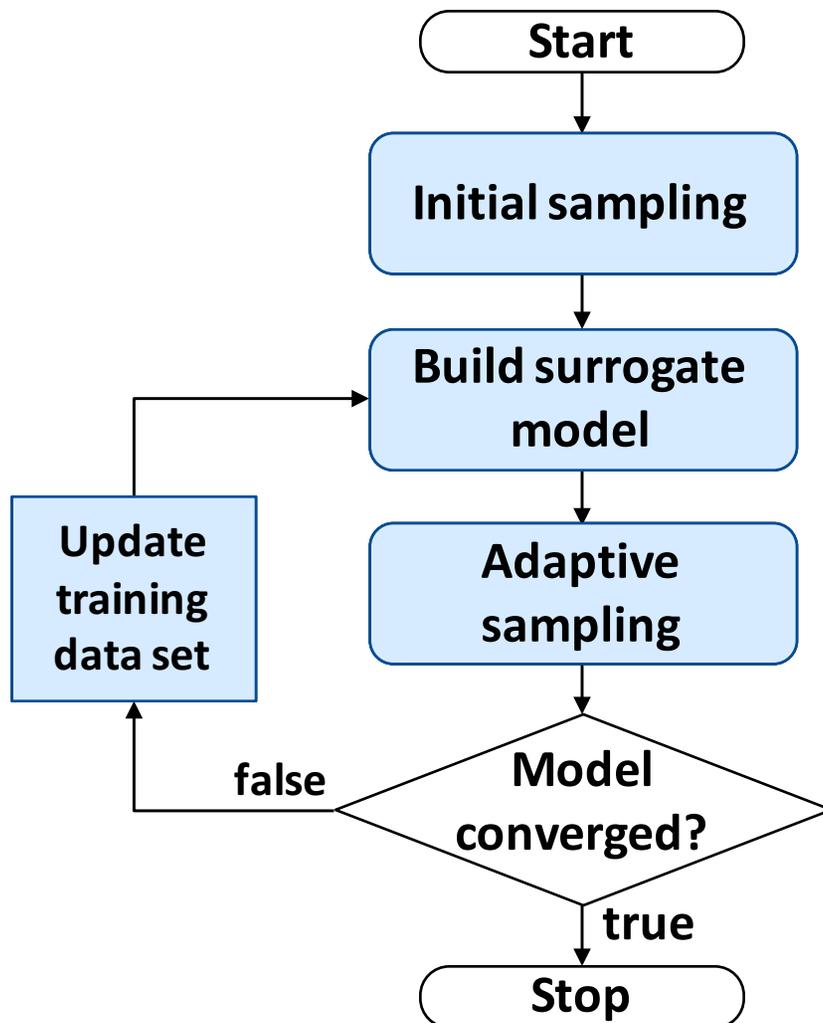
$$\hat{f}(x) = \sum_{i=1}^n \gamma_i \exp\left(\frac{\|x\|}{\sigma^2}\right) + \beta_0 + \beta_1 x + \dots$$

$$\hat{f}(x) = \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \beta_4 e^x$$

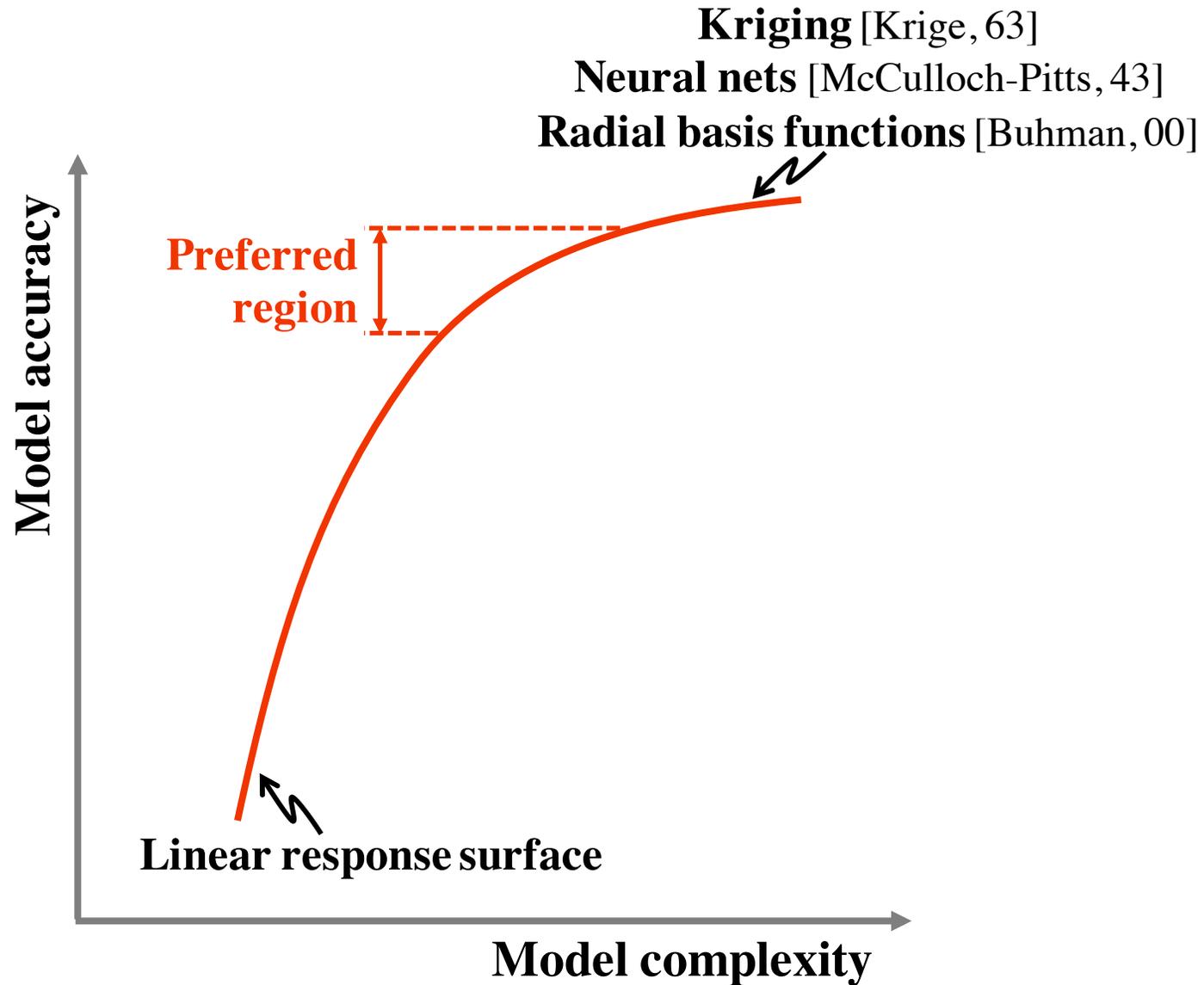
- Generated from a minimal data set
 - *Reduce experimental and simulation requirements*

ALAMO

Automated Learning of Algebraic Models for Optimization



MODEL COMPLEXITY TRADEOFF



MODEL IDENTIFICATION

- Goal: Identify the **functional form** and **complexity** of the surrogate models

$$z = f(x)$$

- Functional form:
 - General functional form is unknown: Our method will identify models with combinations of **simple basis functions**

Category	$X_j(x)$
I. Polynomial	$(x_d)^\alpha$
II. Multinomial	$\prod_{d \in \mathcal{D}' \subseteq \mathcal{D}} (x_d)^{\alpha_d}$
III. Exponential and logarithmic	$\exp\left(\frac{x_d}{\gamma}\right)^\alpha, \log\left(\frac{x_d}{\gamma}\right)^\alpha$
IV. Expected bases	From experience, simple inspection, physical phenomena, etc.

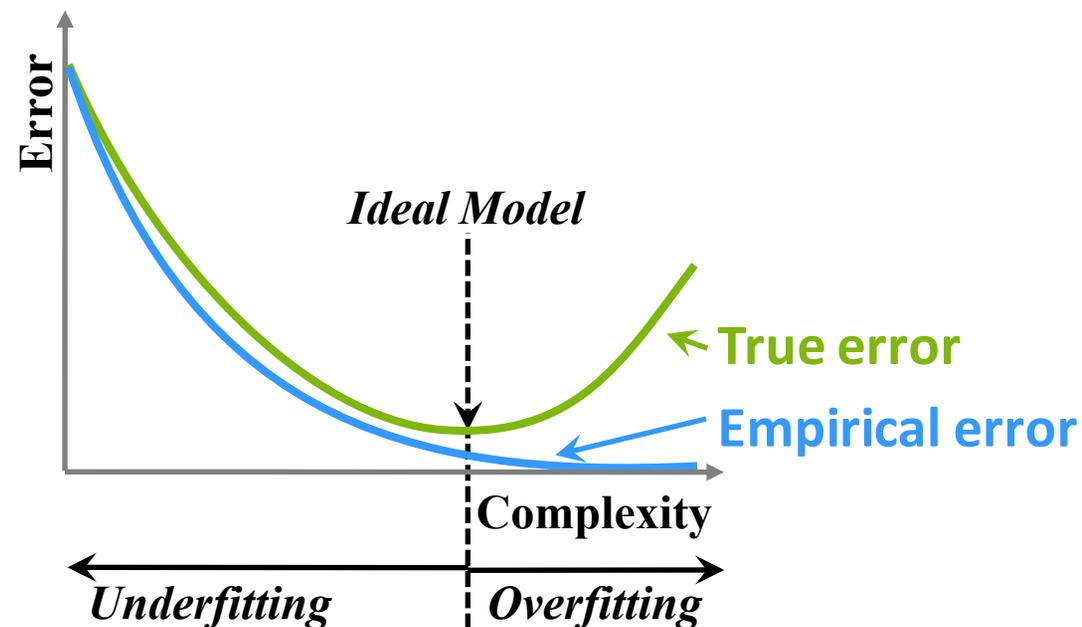
OVERFITTING AND TRUE ERROR

- **Step 1:** Define a large set of potential basis functions

$$\hat{z}(x) = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2 + \beta_4 e^{x_1} + \beta_5 e^{x_2} + \dots$$

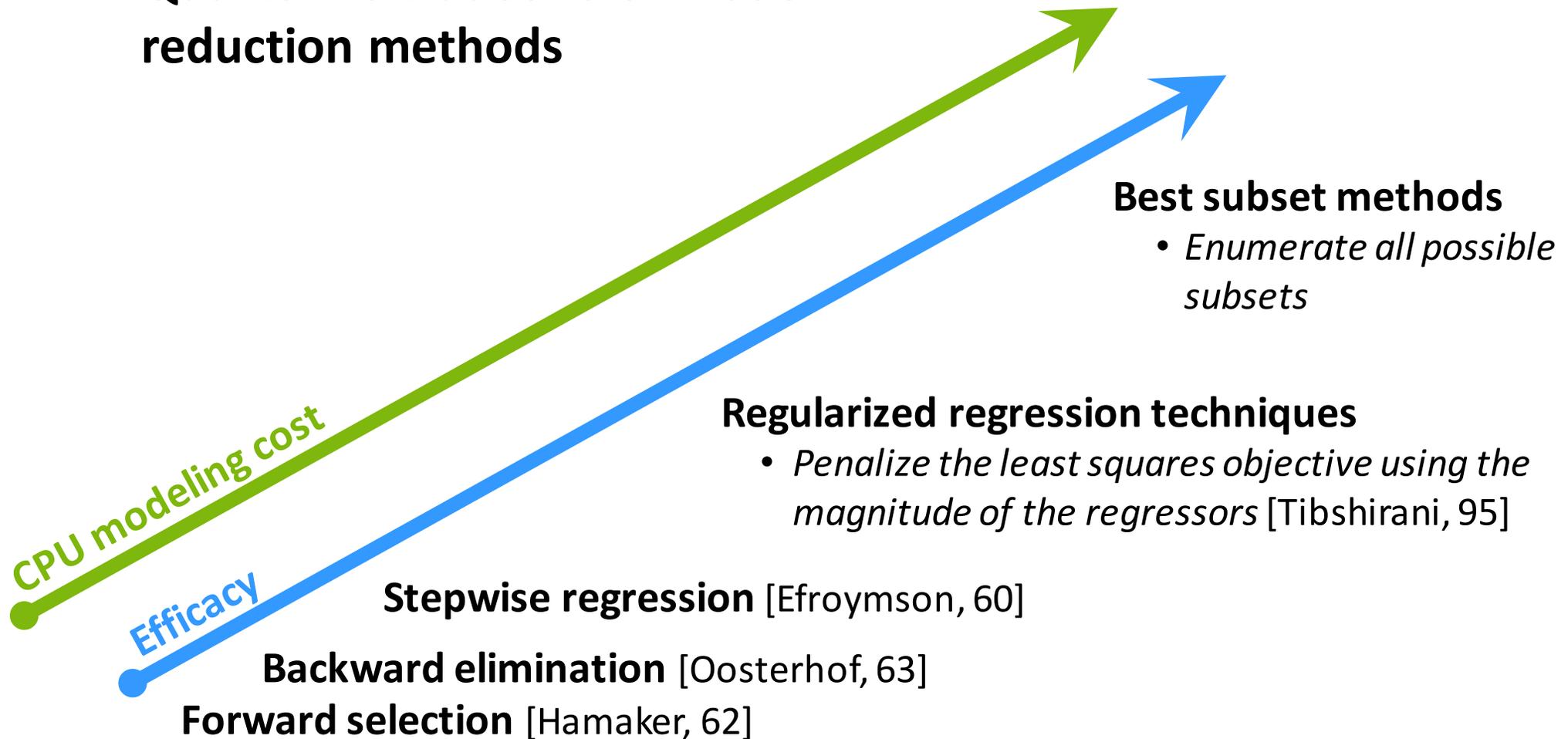
- **Step 2:** Model reduction

$$\hat{z}(x) = 2 + x_2 + 5 e^{x_1}$$

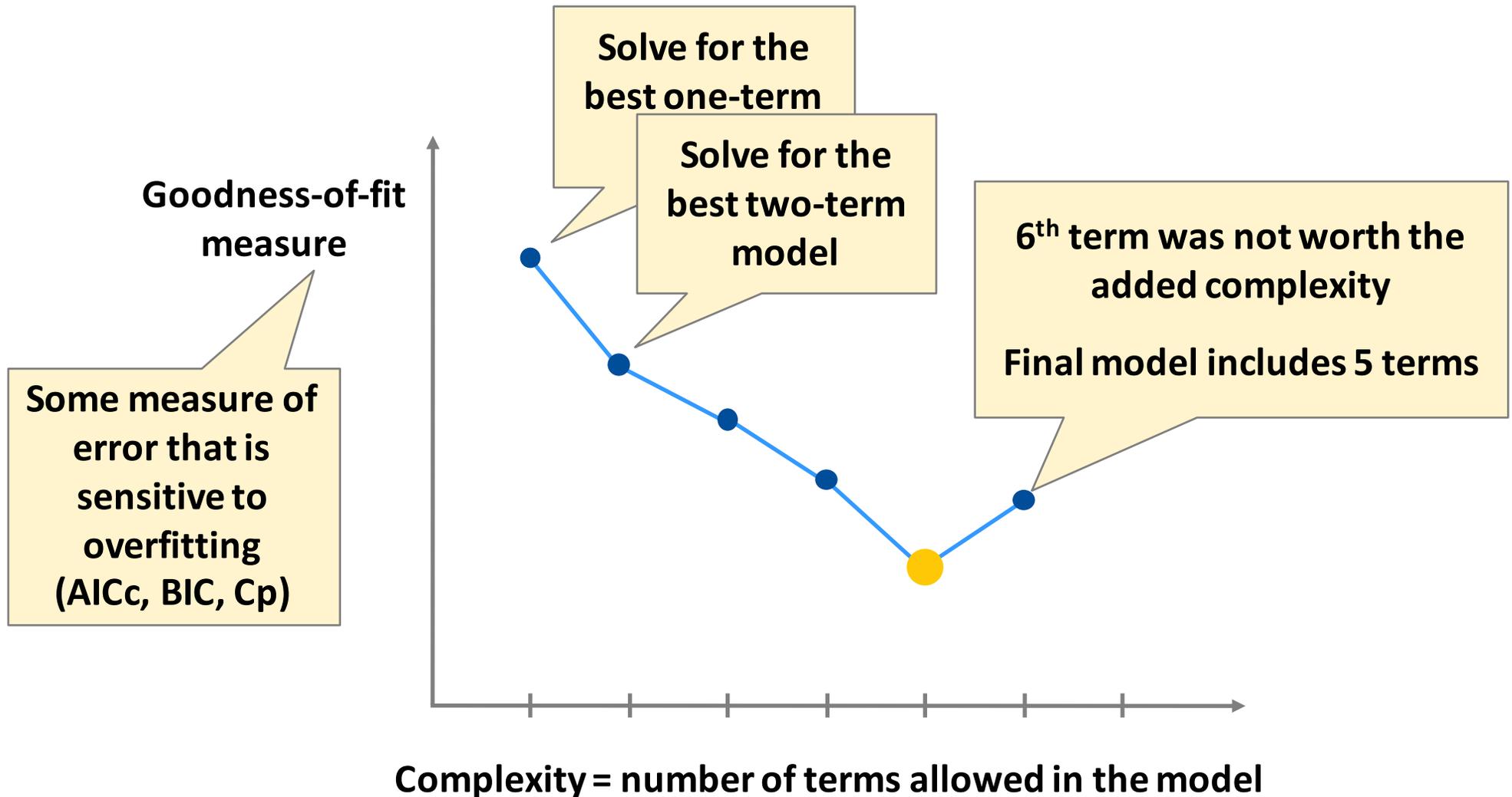


MODEL REDUCTION TECHNIQUES

- Qualitative tradeoffs of model reduction methods



MODEL SIZING



BASIS FUNCTION SELECTION

$$\min SE = \sum_{i=1}^N \left| z_i - \sum_{j \in \mathcal{B}} \beta_j X_{ij} \right|$$

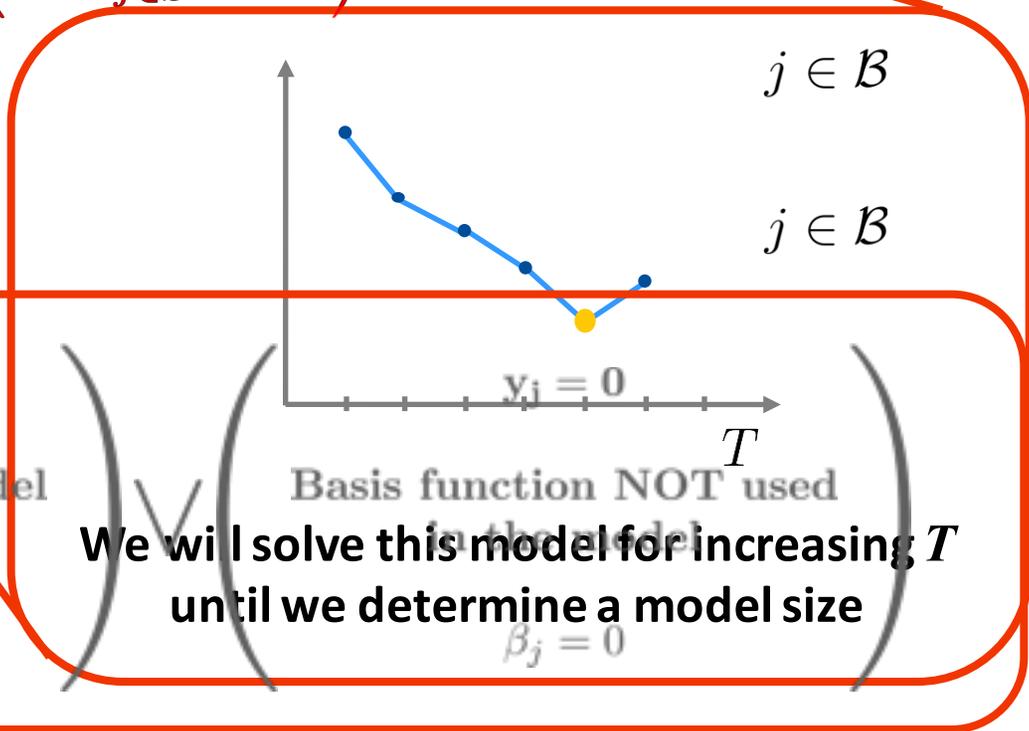
Find the model with the least error

$$\text{s.t. } \sum_{j \in \mathcal{B}} y_j = T$$

$$-U(1 - y_j) \leq \sum_{i=1}^N X_{ij} \left(z^i - \sum_{j \in \mathcal{B}} \beta_j X_{ij} \right) \leq U(1 - y_j) \quad j \in \mathcal{B}$$

$$\beta^l y_j \leq \beta_j \leq \beta^u y_j$$

$$y_j = \{0, 1\}$$

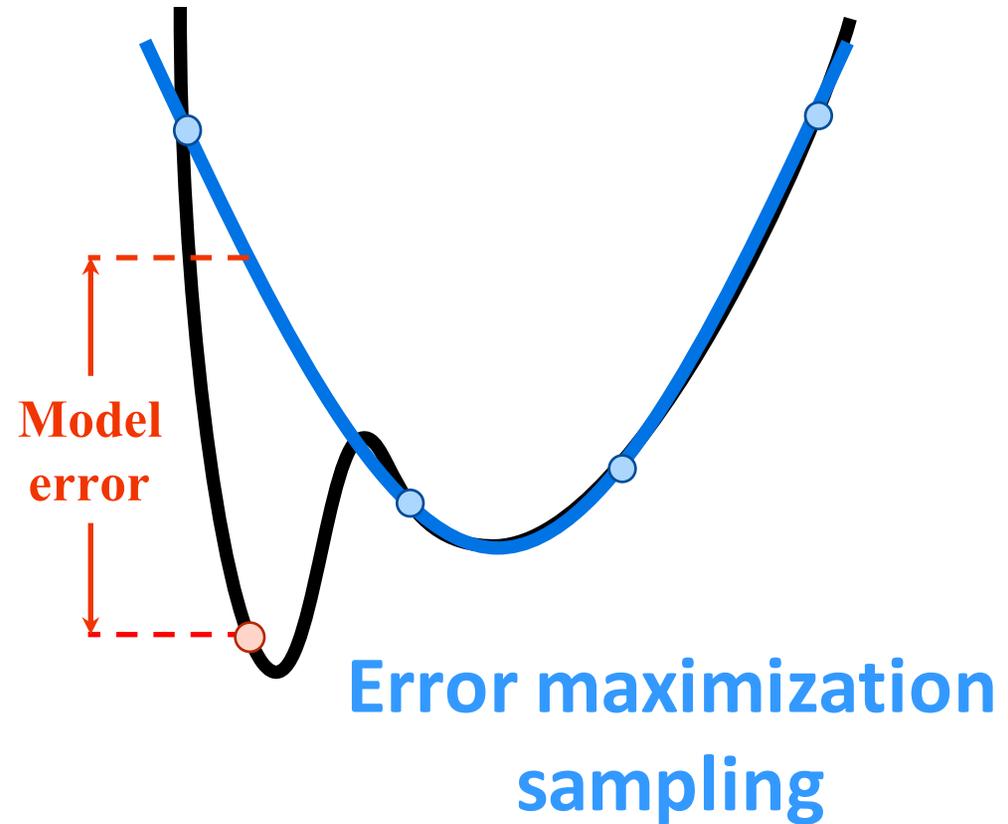
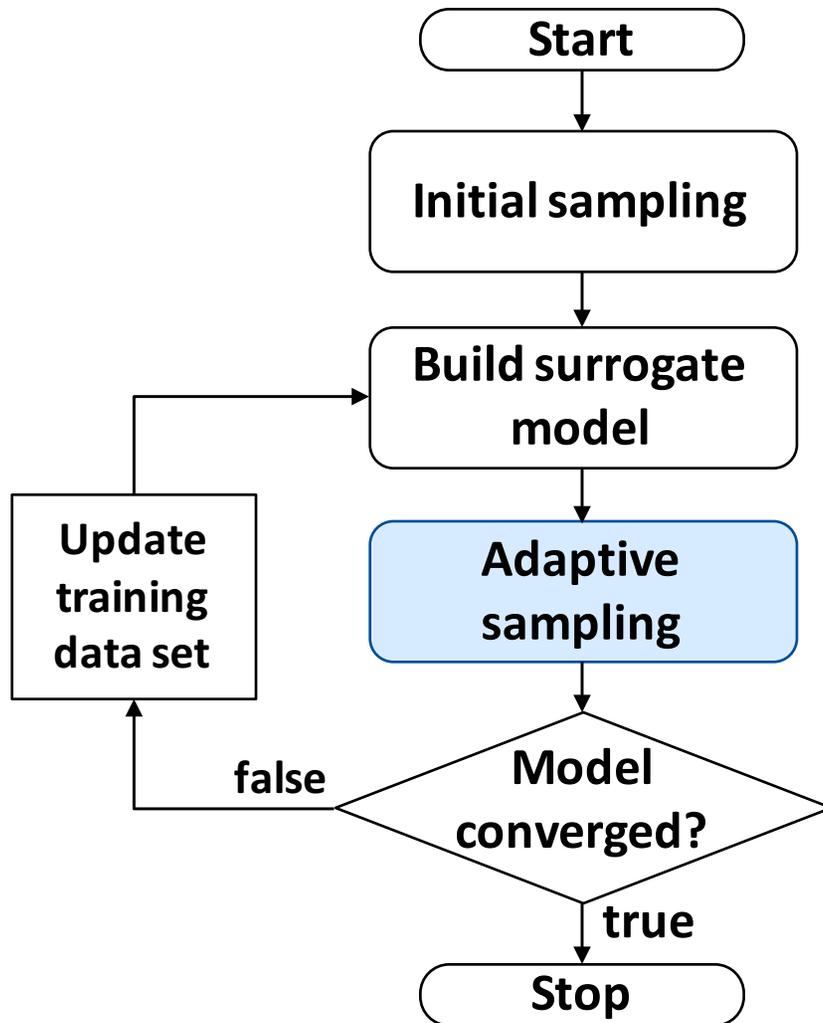


$y_j = 1$
 Basis function used in the model
 β_j is chosen to satisfy a least squares regression
 (assumes loose bounds on β_j)

$y_j = 0$
 Basis function NOT used in the model
 $\beta_j = 0$
 We will solve this model for increasing T until we determine a model size

ALAMO

Automated Learning of Algebraic Models for Optimization



ERROR MAXIMIZATION SAMPLING

- Search the problem space for areas of model inconsistency or model mismatch
- Find points that maximize the model error with respect to the independent variables

$$\max_x \left(\frac{z(x) - \hat{z}(x)}{z(x)} \right)^2$$

Surrogate model

- Derivative-free solvers work well in low-dimensional spaces
[Rios and Sahinidis, 12]
- Optimized using a black-box or derivative-free solver (SNOBFIT)
[Huyer and Neumaier, 08]

COMPUTATIONAL RESULTS

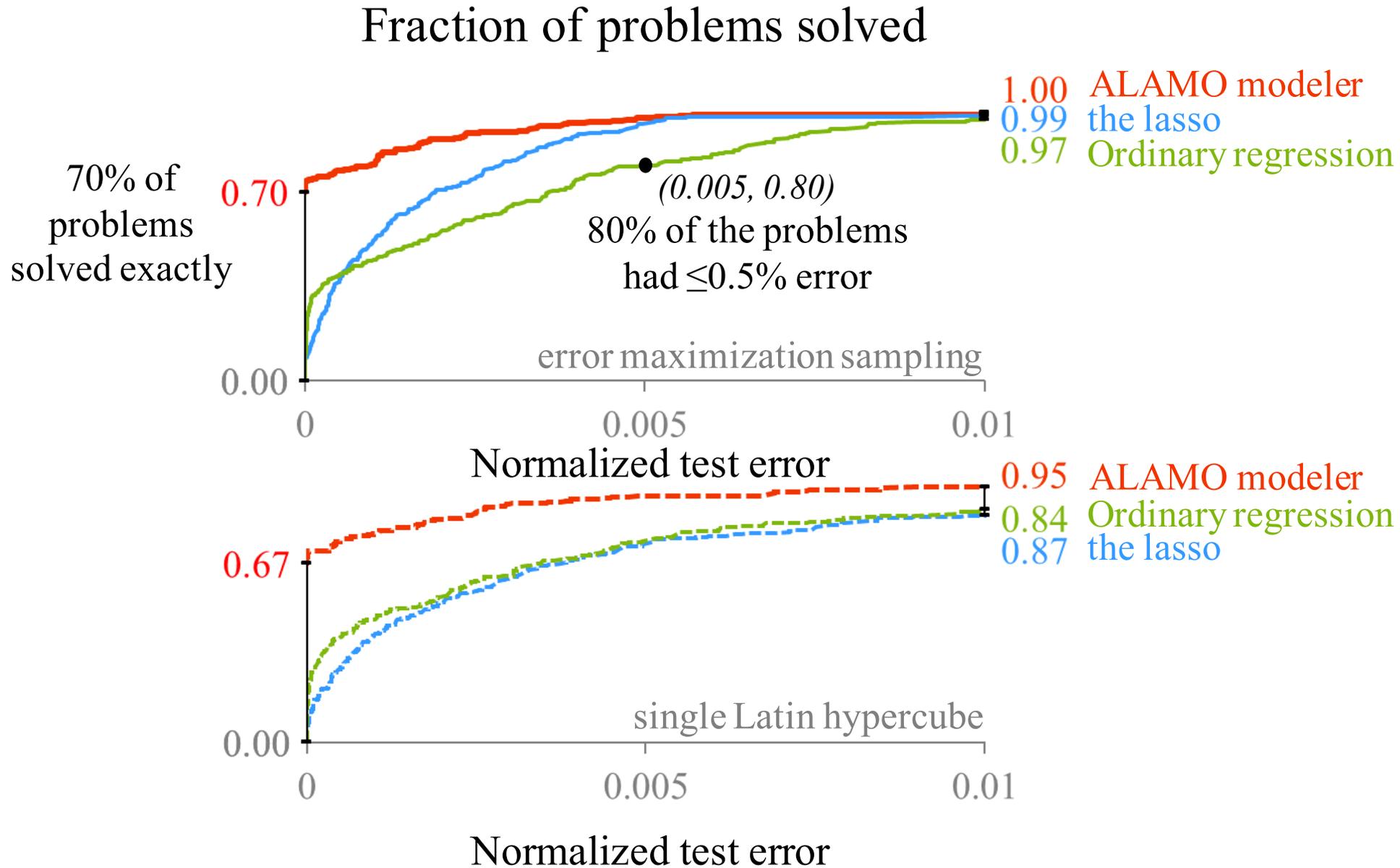
- Goal – Compare methods on three target metrics

1 Model accuracy

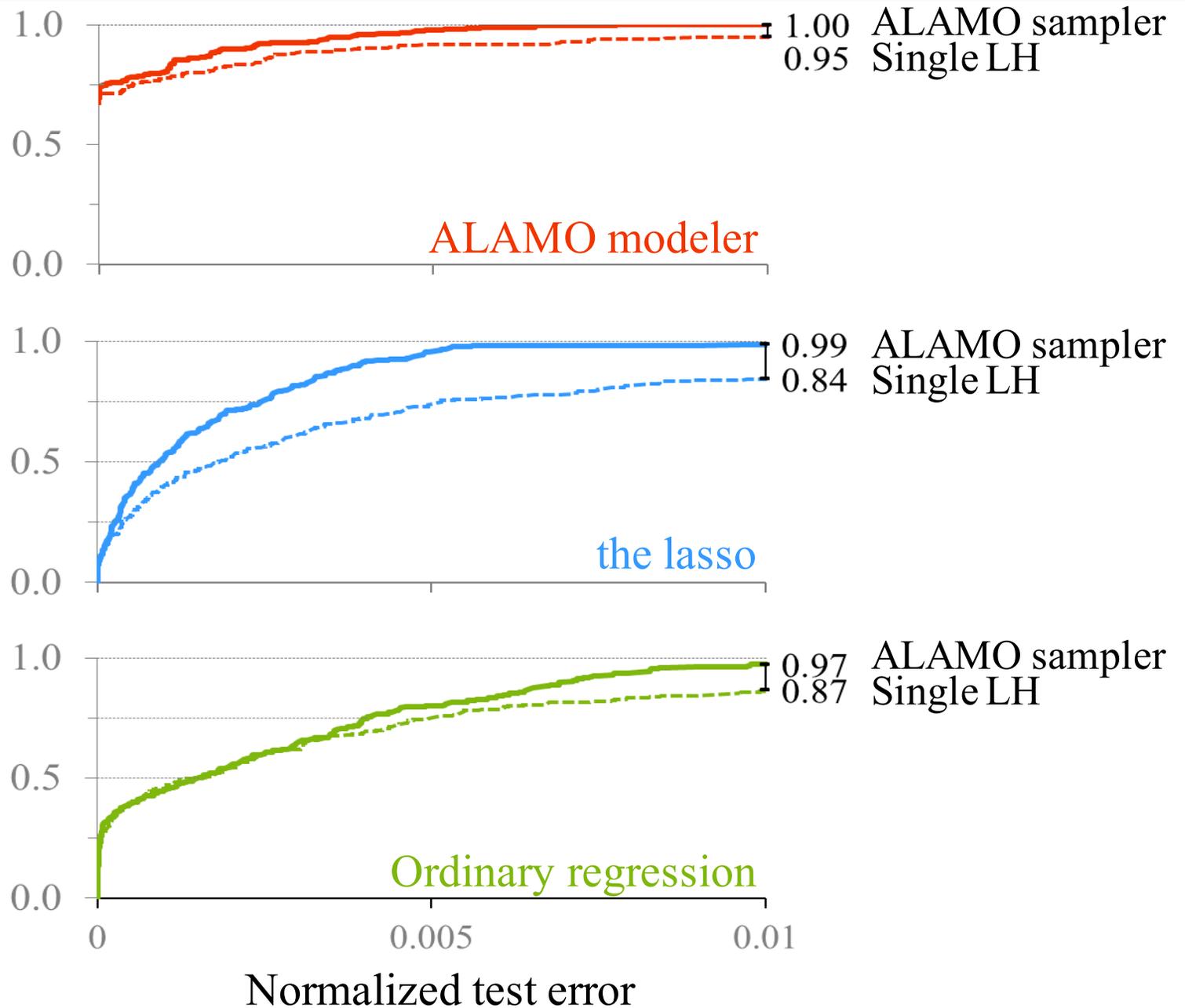
2 Data efficiency

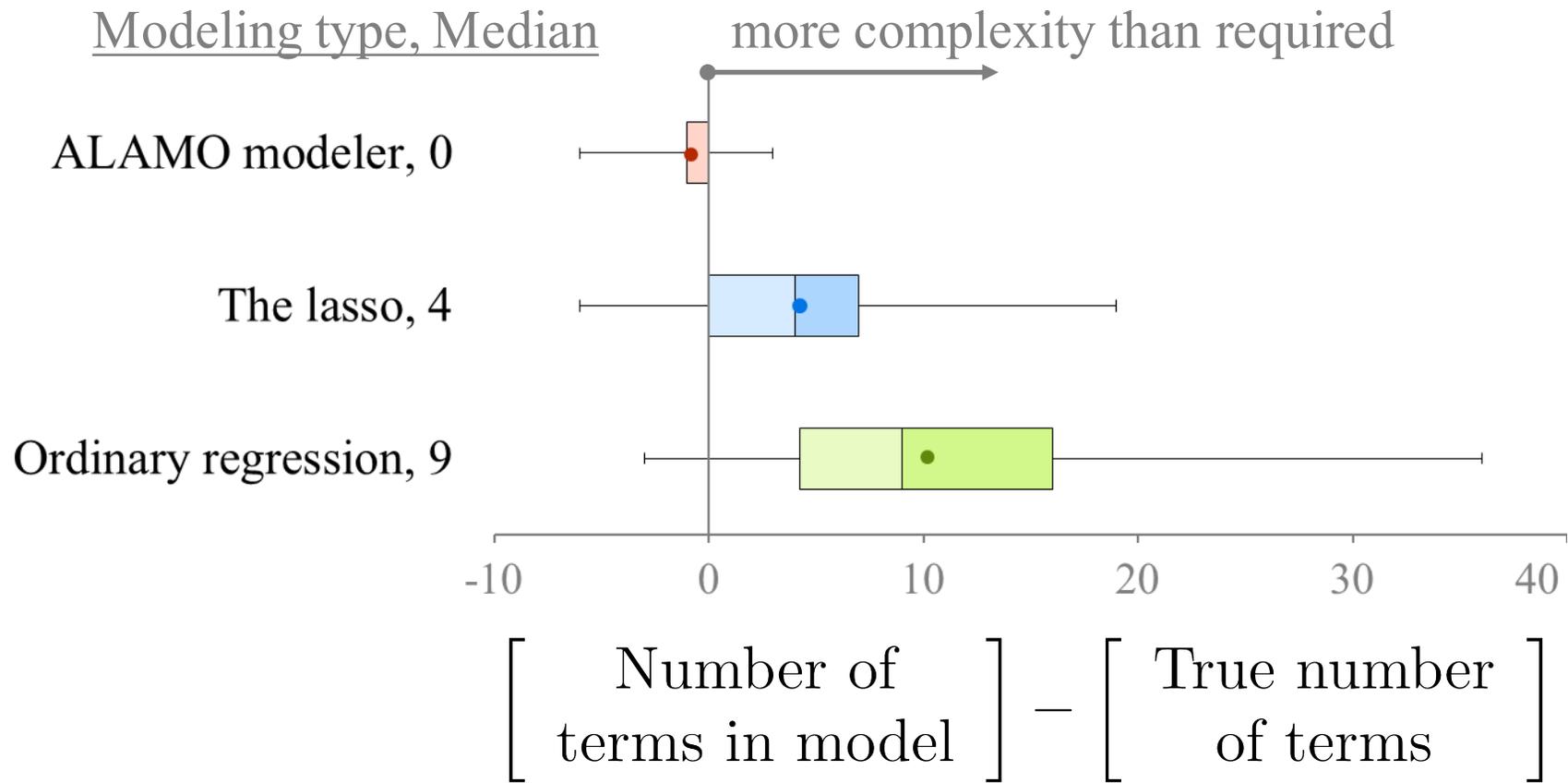
3 Model simplicity

- Modeling methods compared
 - **ALAMO modeler** – Proposed methodology
 - **The LASSO** – The lasso regularization
 - **Ordinary regression** – Ordinary least-squares regression
- Sampling methods compared (over the same data set size)
 - ALAMO sampler – Proposed error maximization technique
 - Single LH – Single Latin hypercube (no feedback)



Fraction of problems solved





Results over a test set of 45 known functions treated as black boxes with bases that are available to all modeling methods.

MODEL SELECTION CRITERIA

- Balance fit (sum of square errors) with model complexity (number of terms in the model; denoted by p)

Corrected Akaike Information Criterion

$$AIC_c = N \log \left(\frac{1}{N} \sum_{i=1}^N (z_i - X_i \beta)^2 \right) + 2p + \frac{2p(p+1)}{N-p-1}$$

Mallows' Cp

$$C_p = \frac{\sum_{i=1}^N (z_i - X_i \beta)^2}{\widehat{\sigma}^2} + 2p - N$$

Hannan-Quinn Information Criterion

$$HQC = N \log \left(\frac{1}{N} \sum_{i=1}^N (z_i - X_i \beta)^2 \right) + 2p \log(\log(N))$$

Bayes Information Criterion

$$BIC = \frac{\sum_{i=1}^N (z_i - X_i \beta)^2}{\widehat{\sigma}^2} + p \log(N)$$

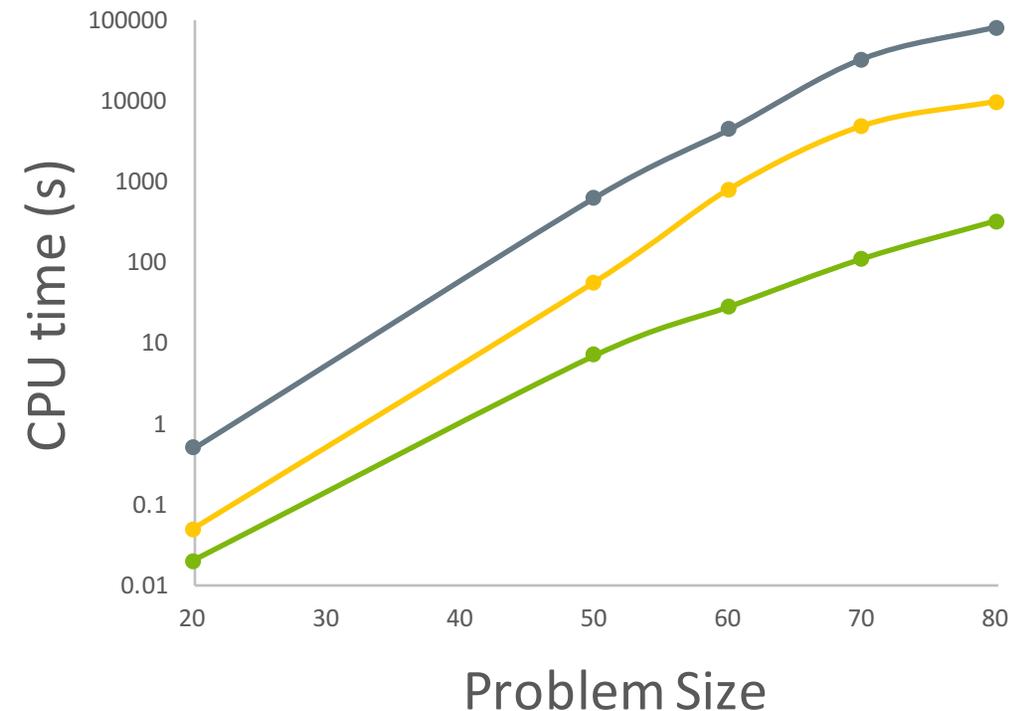
Mean Squared Error

$$MSE = \frac{\sum_{i=1}^N (z_i - X_i \beta)^2}{N - p - 1}$$

CPU TIME COMPARISON

- Eight benchmarks from the UCI and CMU data sets
- Seventy noisy data sets were generated with multicollinearity and increasing problem size (number of bases)

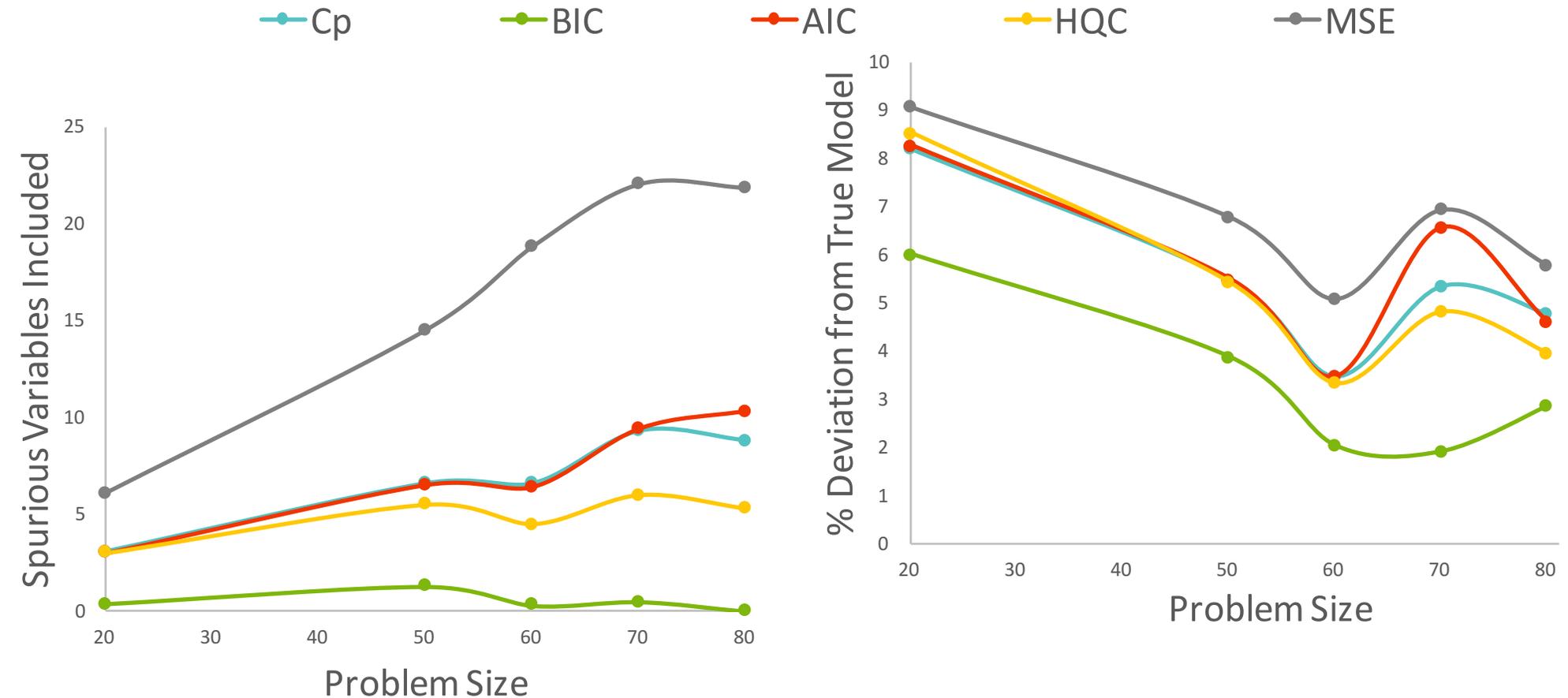
— Cp — BIC — AIC, MSE, HQC



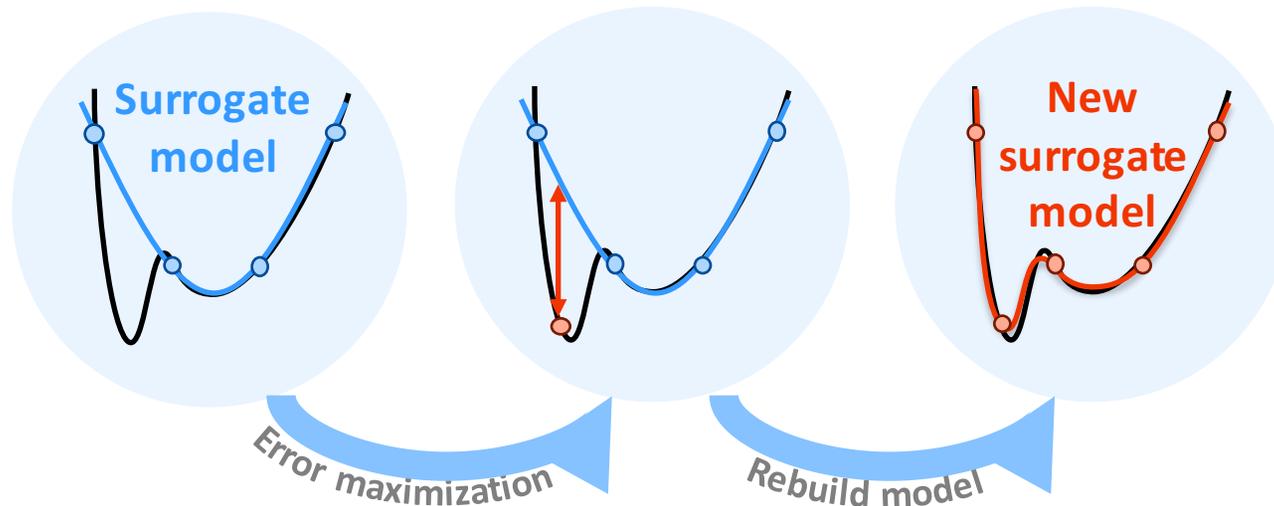
- **BIC solves more than two orders of magnitude faster than AIC, MSE and HQC**
 - Optimized directly via a single mixed-integer convex quadratic model

MODEL QUALITY COMPARISON

- **BIC leads to smaller, more accurate models**
 - Larger penalty for model complexity

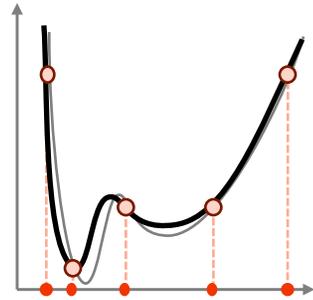


ALAMO REMARKS

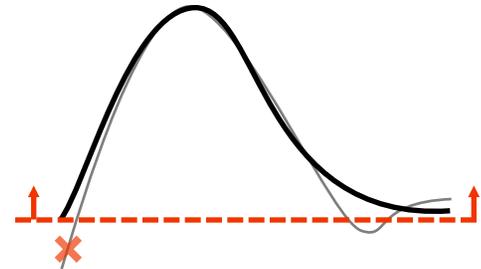


- **Expanding the scope of algebraic optimization**
 - Using low-complexity surrogate models to strike a balance between optimal decision-making and model fidelity
- **Surrogate model identification**
 - Simple, accurate model identification – Integer optimization
- **Error maximization sampling**
 - More information found per simulated data point

THEORY UTILIZATION



empirical data



non-empirical information

- Use **freely available** system knowledge to strengthen model
 - Physical limits
 - First-principles knowledge
 - Intuition
- Non-empirical restrictions can be applied to general regression problems

CONSTRAINED REGRESSION

- Challenging due to the semi-infinite nature of the regression constraints

Standard regression

$$\min_{\beta_1, \beta_2} \sum_{i=1}^4 (z_i - \hat{z}(x_i; \beta_1, \beta_2))^2$$

Surrogate
model

easy

$$\begin{aligned} \min_{\beta_1, \beta_2} & \sum_{i=1}^4 (z_i - \hat{z}(x_i; \beta_1, \beta_2))^2 \\ \text{s.t.} & \beta_1 \geq \beta_2 \end{aligned}$$

tough

$$\begin{aligned} \min_{\beta_1, \beta_2} & \sum_{i=1}^4 (z_i - \hat{z}(x_i; \beta_1, \beta_2))^2 \\ \text{s.t.} & \hat{z}(x_i; \beta_1, \beta_2) \geq 0 \quad \forall x \end{aligned}$$

IMPLIED PARAMETER RESTRICTIONS

Find a model \hat{z} such that $\hat{z}(x) \geq 0$ with a fixed model form:

$$\hat{z}(x) = \beta_1 x + \beta_2 x^3$$

**Step 1: Formulate
constraint in z- and x-space**

$$\min_{\beta_1, \beta_2} \sum_{i=1}^4 (z_i - [\beta_1 x + \beta_2 x^3])^2$$

$$\text{s.t. } \beta_1 x + \beta_2 x^3 \geq 0 \quad x \in [0, 1]$$

1 parametric
constraint

4 β -constraints

**Step 2: Identify a sufficient
set of β -space constraints**

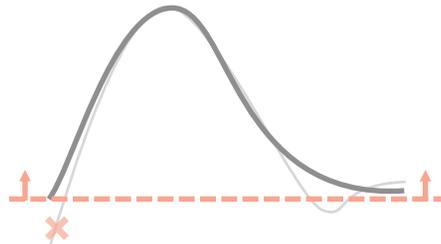
$$\min_{\beta_1, \beta_2} \sum_{i=1}^4 (z_i - [\beta_1 x + \beta_2 x^3])^2$$

$$\text{s.t. } \left\{ \begin{array}{l} 0.240 \beta_1 + 0.0138 \beta_2 \geq 0 \\ 0.281 \beta_1 + 0.0223 \beta_2 \geq 0 \\ 0.120 \beta_1 + 0.00173 \beta_2 \geq 0 \\ 0.138 \beta_1 + 0.00263 \beta_2 \geq 0 \end{array} \right.$$

TYPES OF RESTRICTIONS

Response bounds

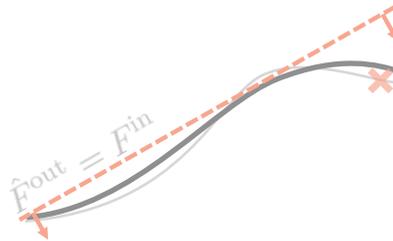
$$[\hat{A}]_t \geq 0$$



pressure, temperature,
compositions

Individual responses

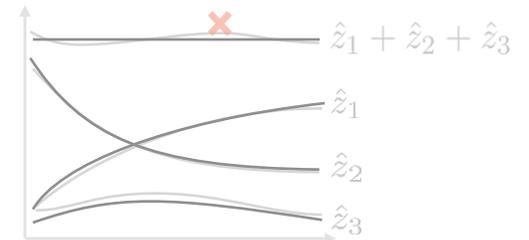
$$\hat{F}^{\text{out}}(x) \leq F^{\text{in}}$$



mass and energy balances,
physical limitations

Multiple responses

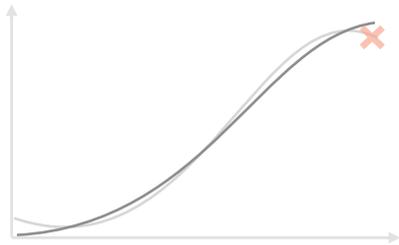
$$\hat{z}_1 + \hat{z}_2 + \hat{z}_3 = 1$$



mass balances, sum-to-one,
state variables

Response derivatives

$$\frac{dT}{dx} \geq 0$$



monotonicity, numerical
properties, convexity

Alternative domains

← Extrapolation zone →

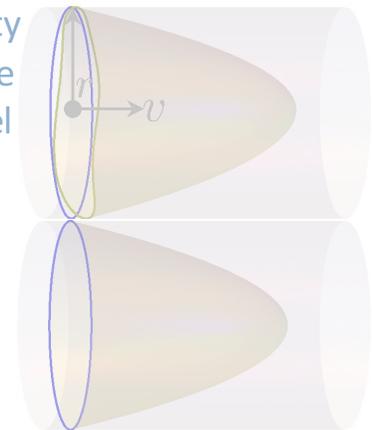


← Problem Space →

safe extrapolation,
boundary conditions

Boundary conditions

velocity
profile
model

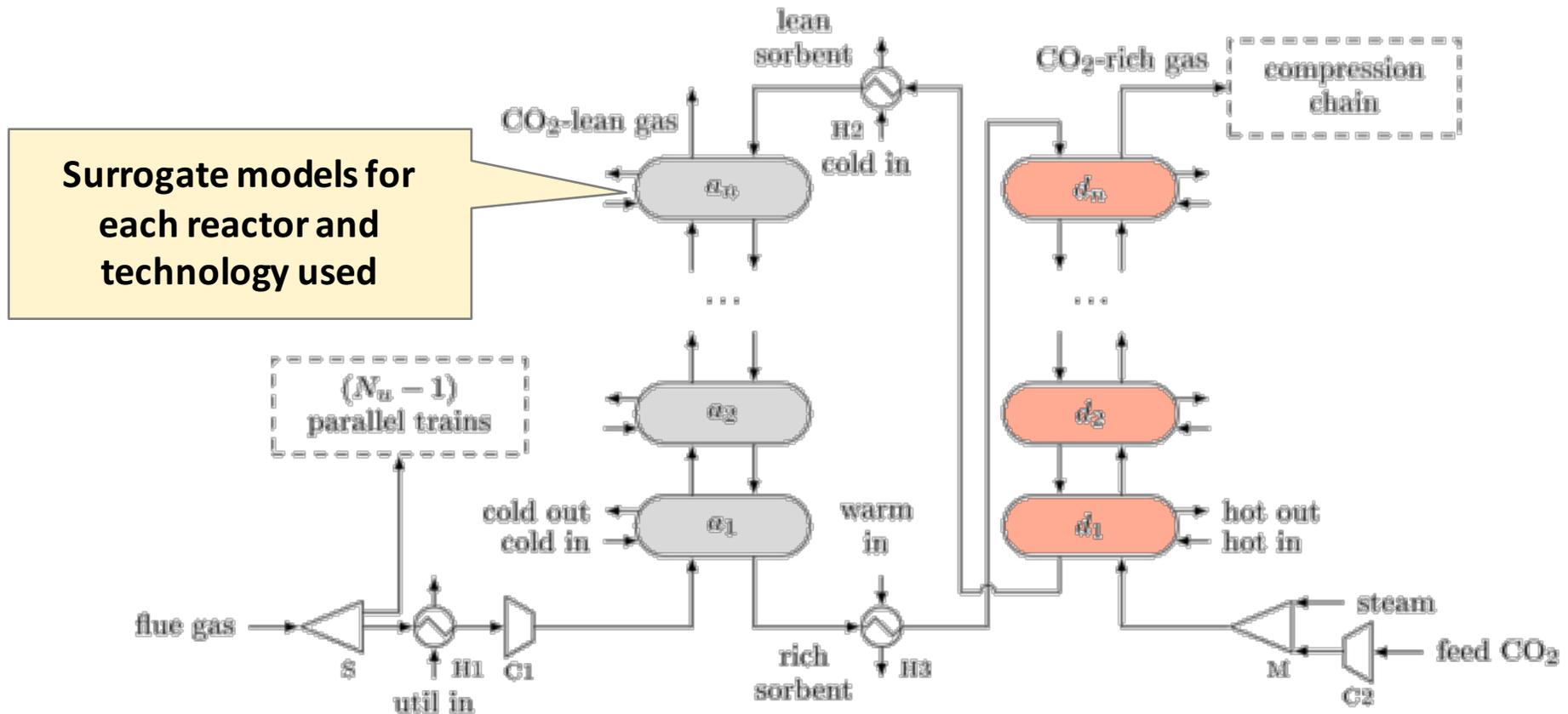


×

Add
no slip

$$\hat{v}(R, \theta) = 0 \quad \forall \theta$$

CARBON CAPTURE SYSTEM DESIGN

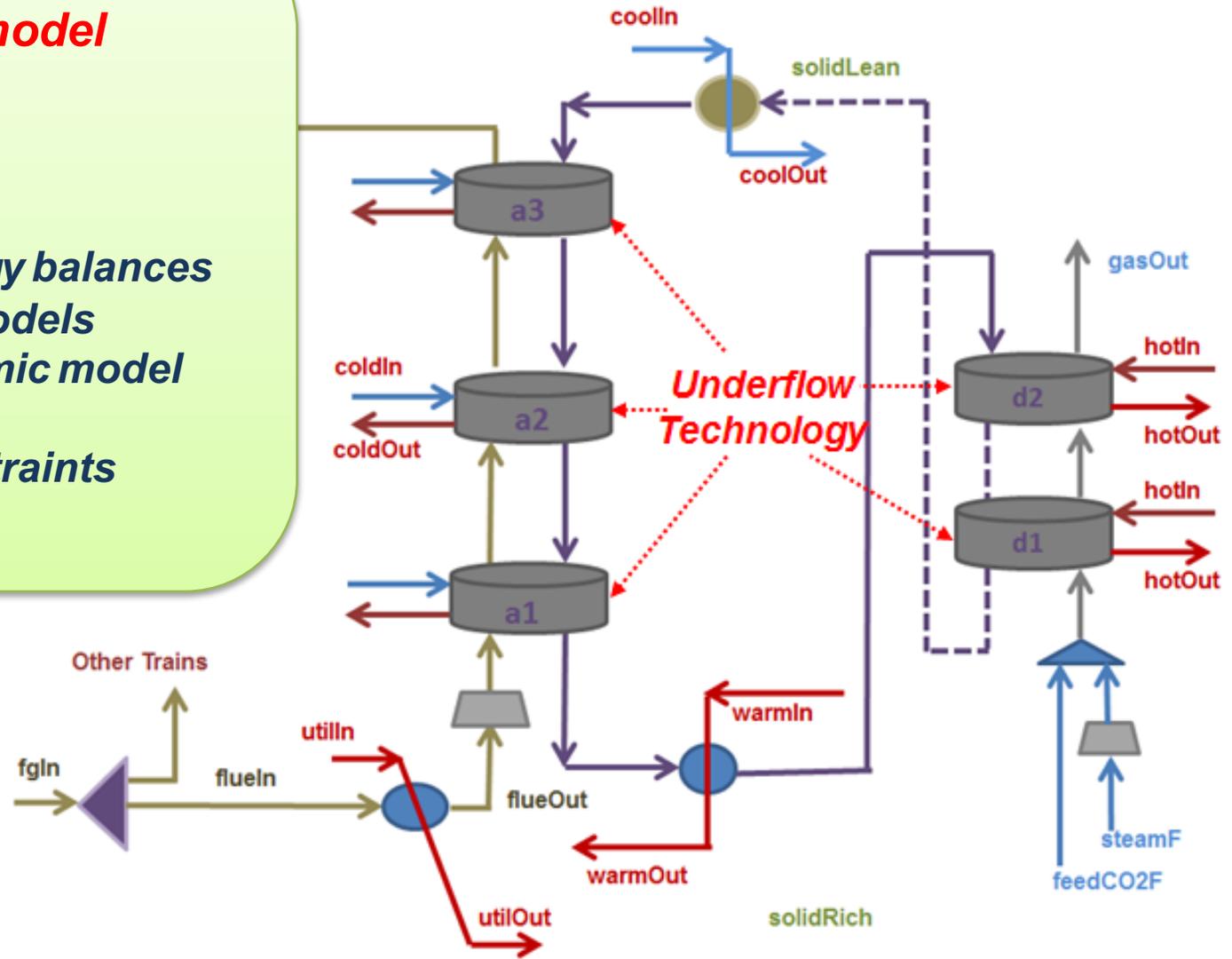


- **Discrete decisions:** How many units? Parallel trains?
What technology used for each reactor?
- **Continuous decisions:** Unit geometries
- **Operating conditions:** Vessel temperature and pressure, flow rates, compositions

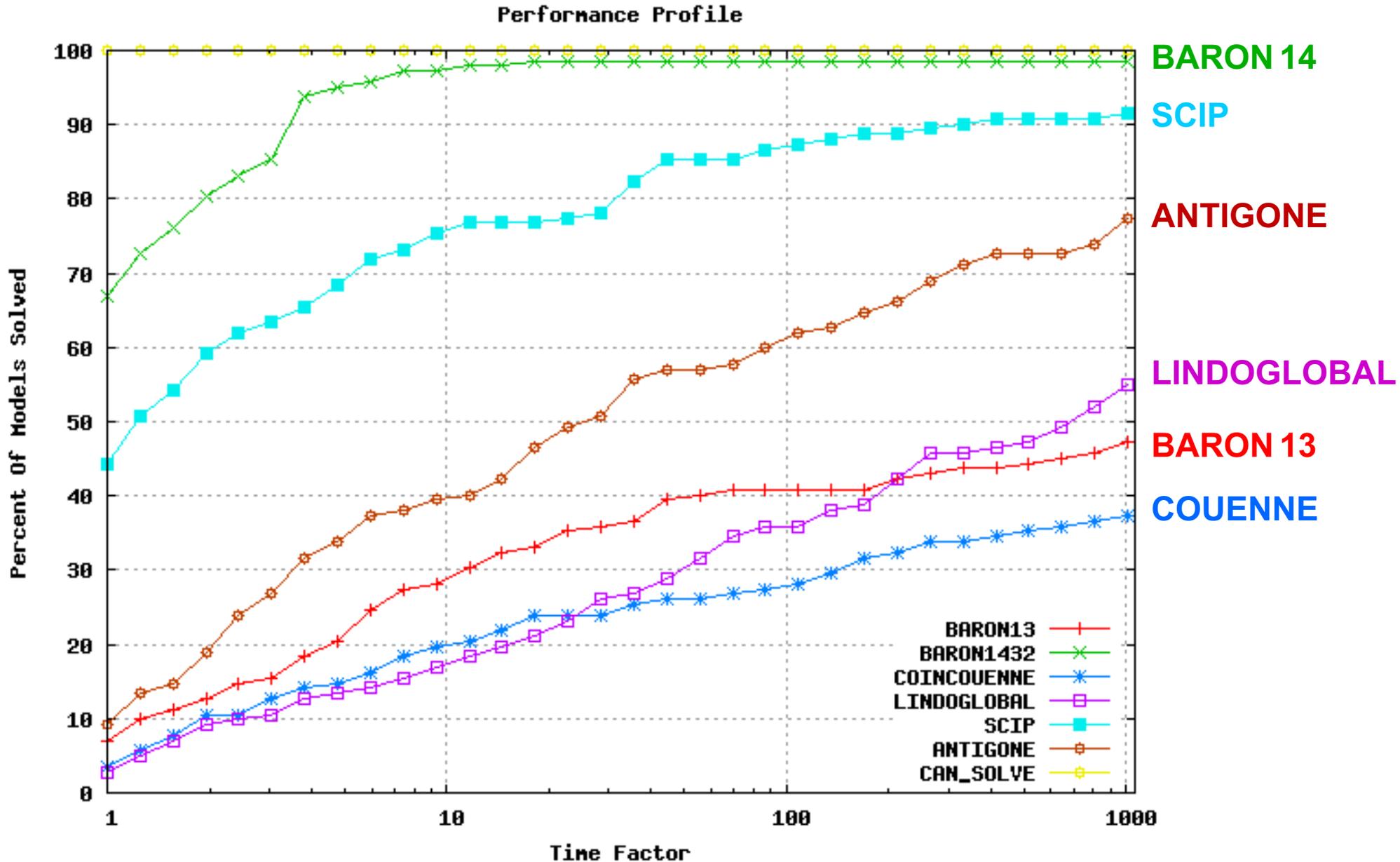
SUPERSTRUCTURE OPTIMIZATION

Mixed-integer nonlinear programming model

- *Economic model*
- *Process model*
- *Material balances*
- *Hydrodynamic/Energy balances*
- *Reactor surrogate models*
- *Link between economic model and process model*
- *Binary variable constraints*
- *Bounds for variables*



GLOBAL MINLP SOLVERS ON CMU/IBMLIB



CONCLUSIONS

- **ALAMO provides algebraic models that are**
 - ✓ Accurate and simple
 - ✓ Generated from a minimal number of function evaluations
- **ALAMO's **constrained regression** facility allows modeling of**
 - ✓ Bounds on response variables
 - ✓ Convexity/monotonicity of response variables
- **On-going efforts**
 - Uncertainty quantification
 - Symbolic regression
- **ALAMO site: archimedes.cheme.cmu.edu/?q=alamo**